

Markus Neteler & GRASS Development Team

Fondazione E. Mach – CRI, Italy

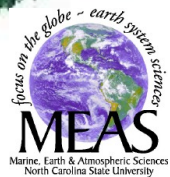
<http://gis.cri.fmach.it>

<http://grass.osgeo.org>

# GRASS GIS 7: your reliable geospatial number cruncher

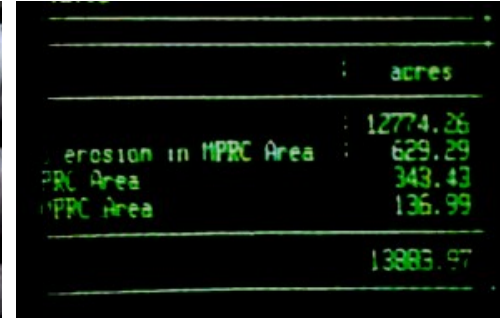


**FOSS4G 2014, Portland (OR), USA  
8 - 13 Sept 2014**



# GRASS GIS 7 User interface

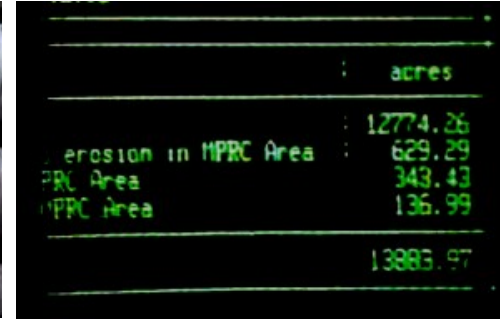
What you think it is...



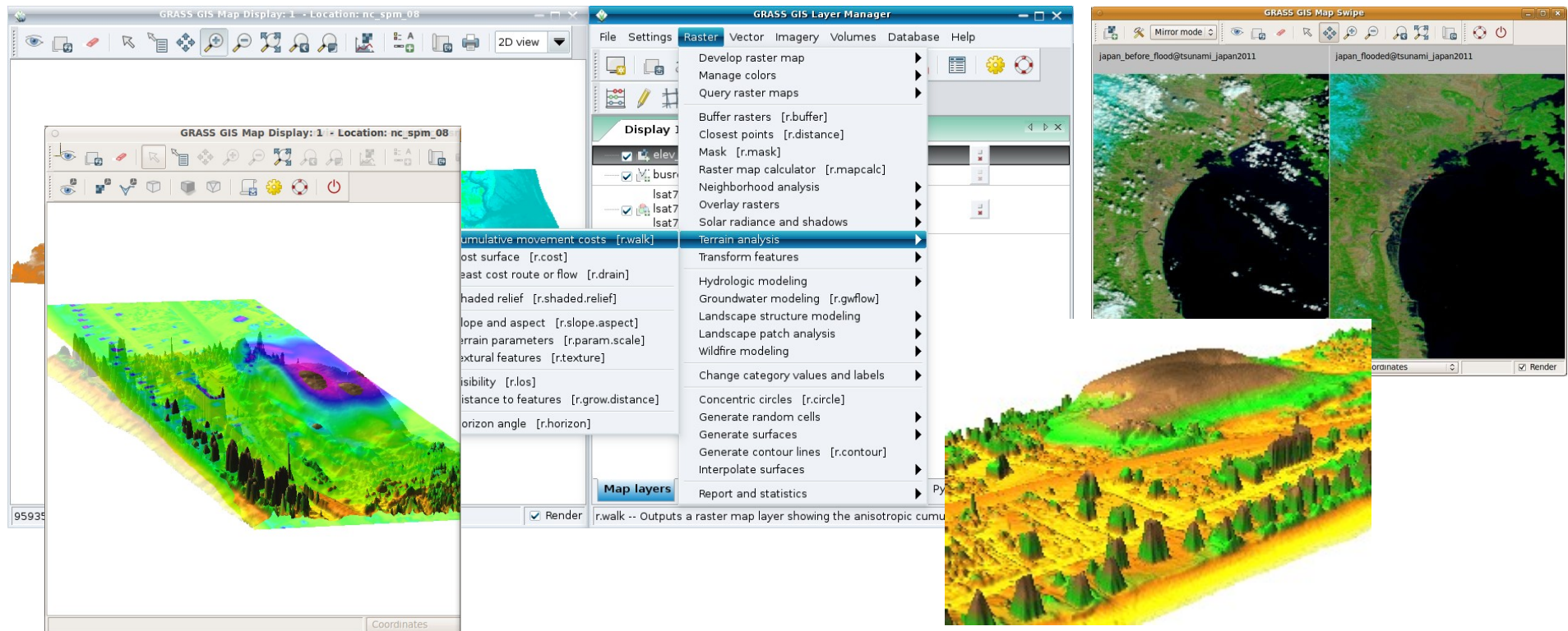


# GRASS GIS 7 User interface

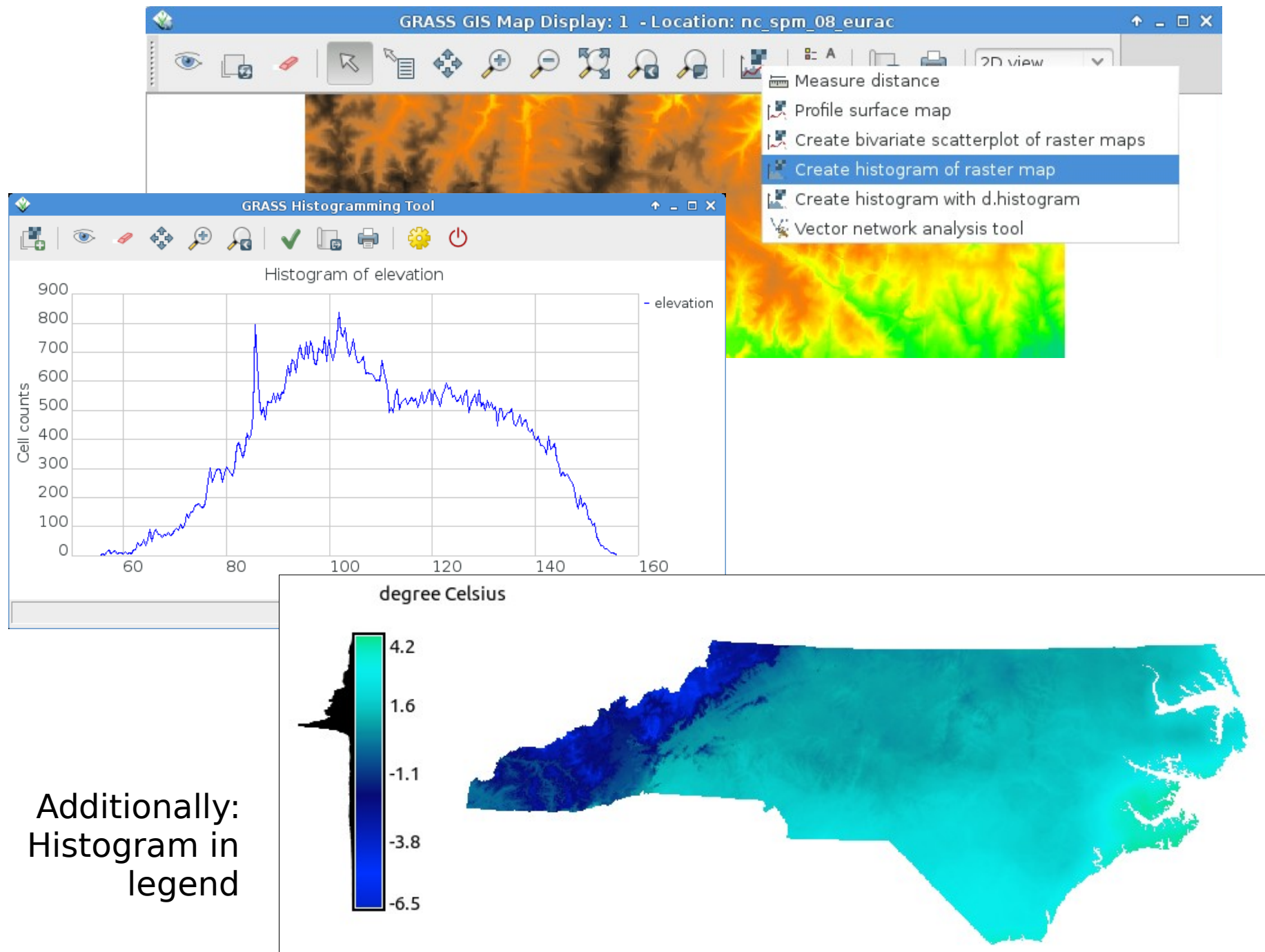
What you think it is...



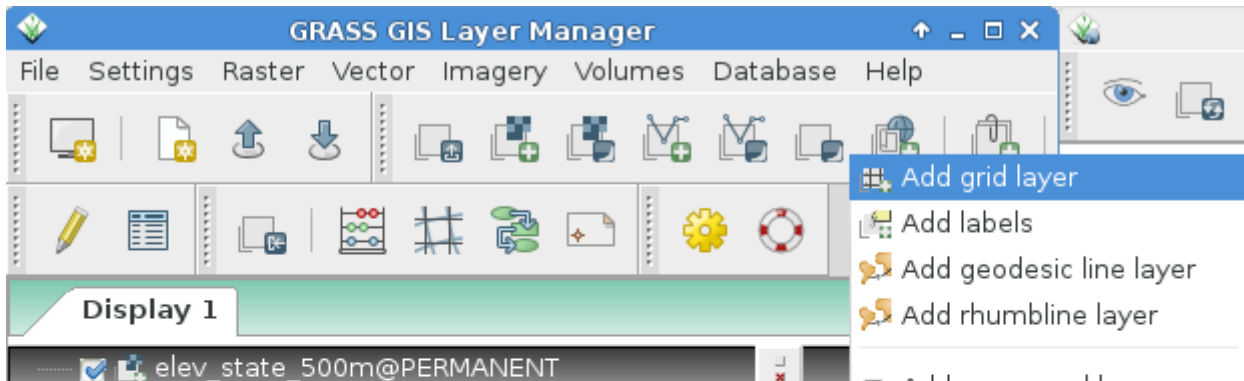
What it really is...



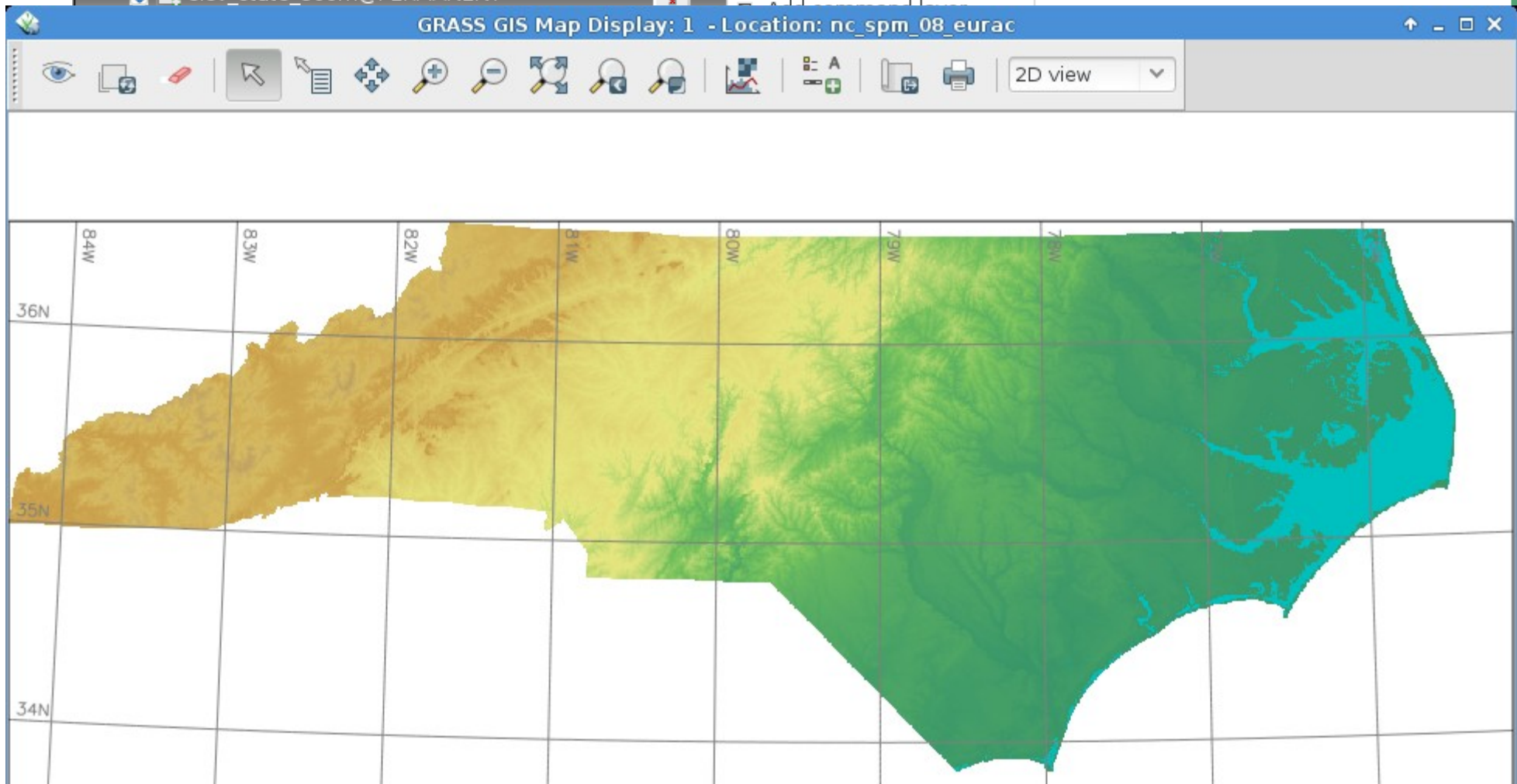
# GRASS 7: Map histogram tool



# GRASS 7: Adding a grid to the map view

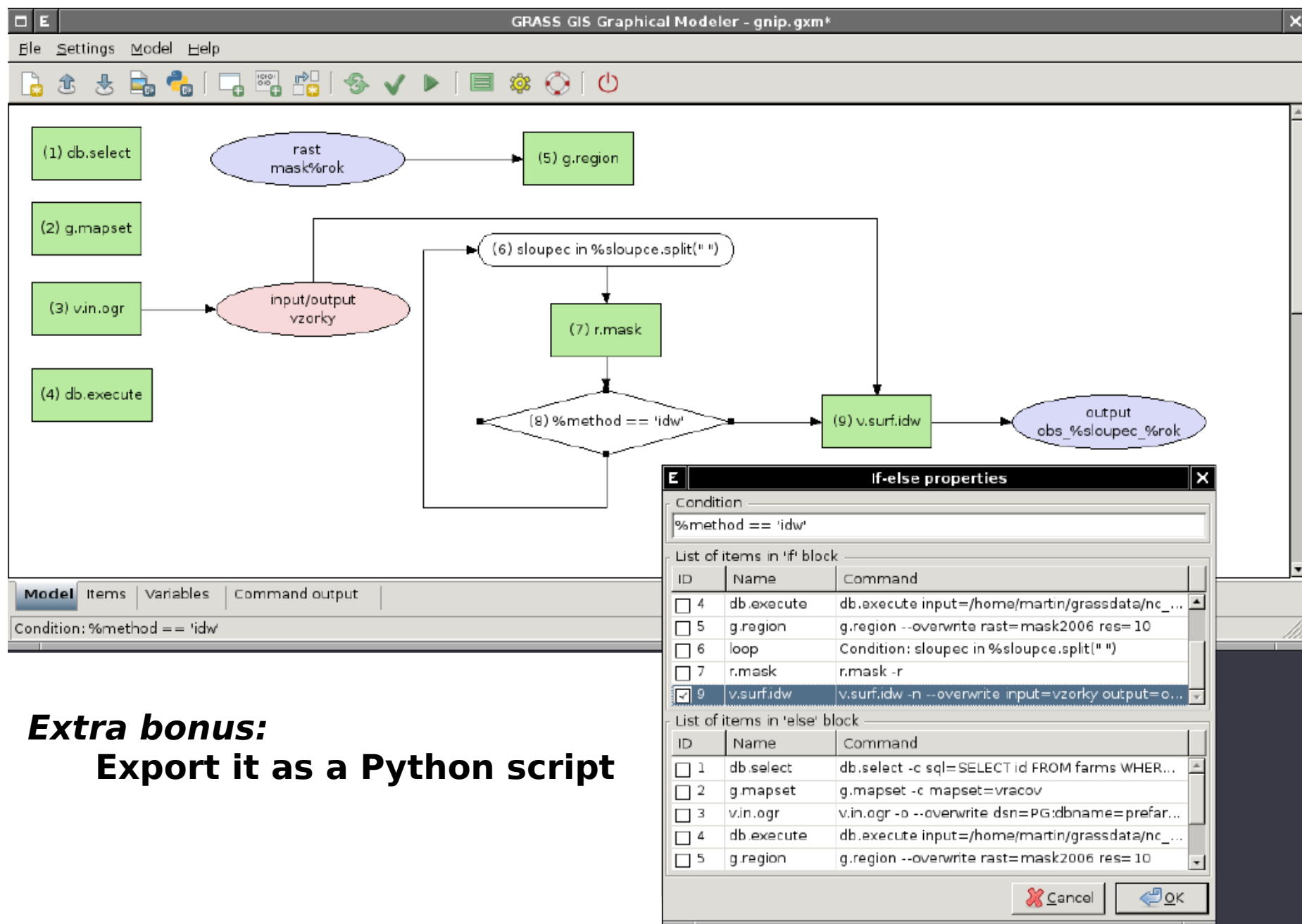


- Grids
- Labels
- Geodesic lines
- Rhumbines



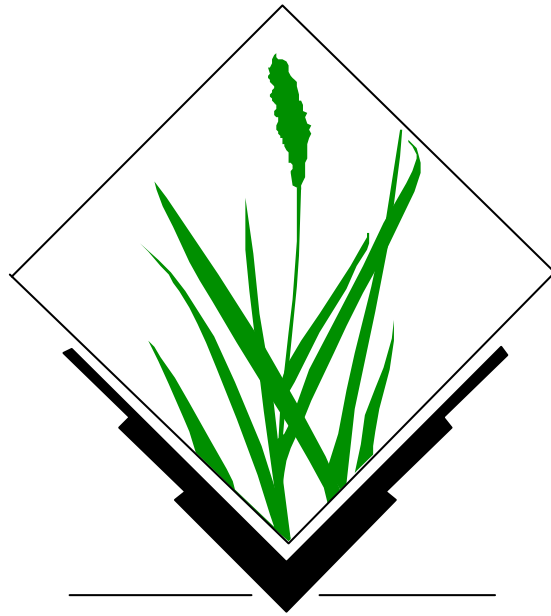


# GRASS 7: New Geospatial Modeller

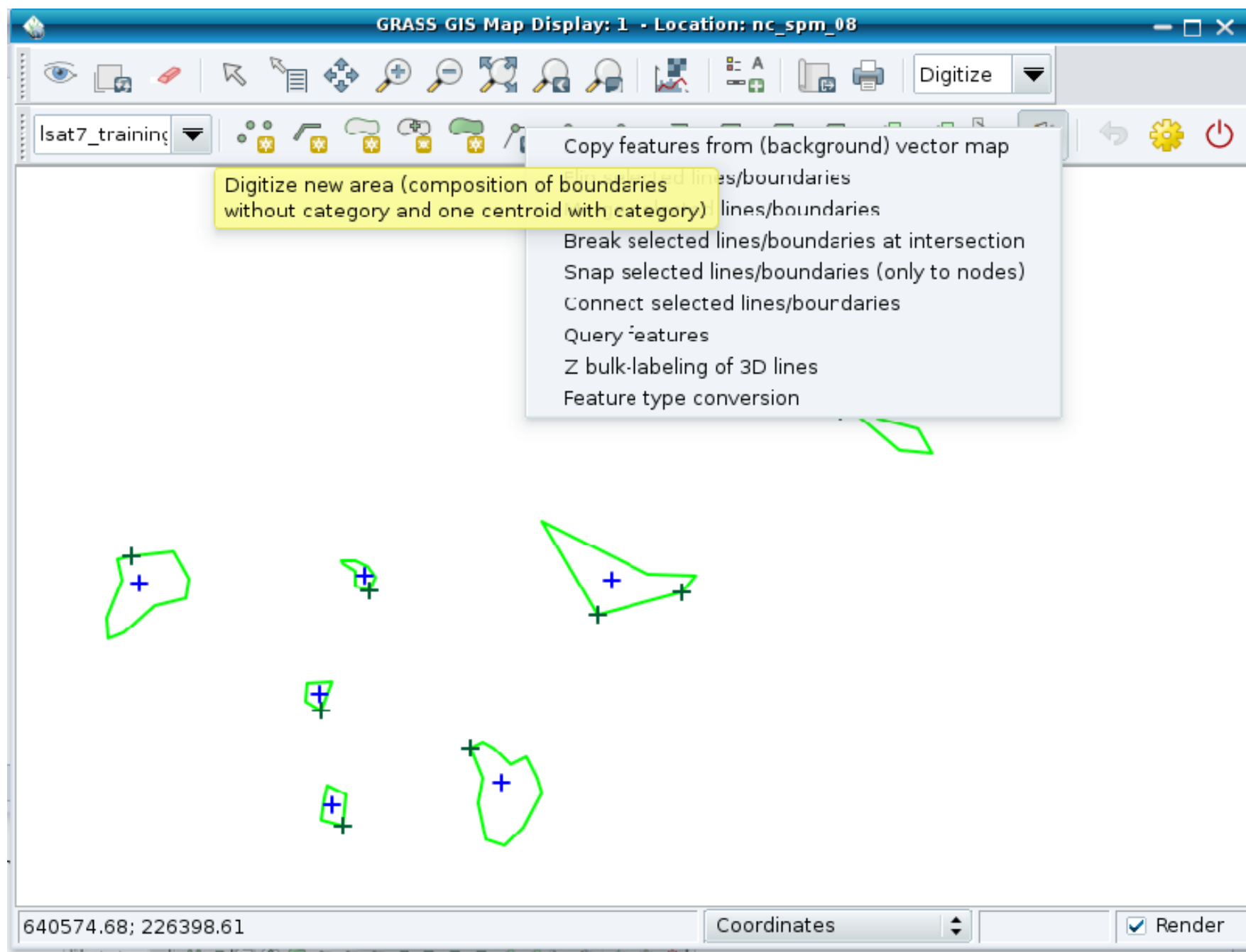


**Extra bonus:**  
**Export it as a Python script**

# Vector data processing



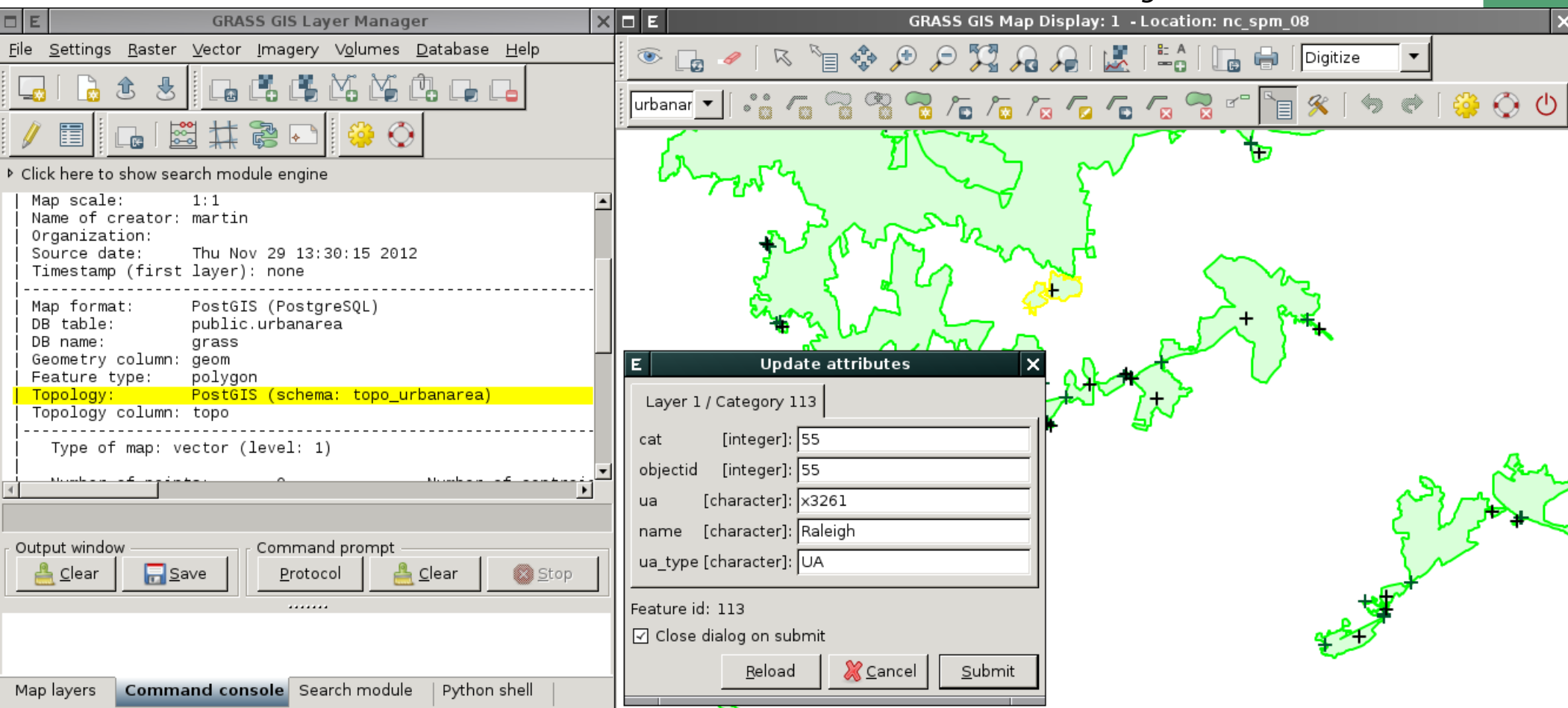
# GRASS 7: Topological Vector Digitizer





# GRASS 7: Topological Vector Digitizer in PostGIS 2 (under development)

Programmer: Martin Landa



<http://grass.osgeo.org/grass70/manuals/v.out.postgis.html>

[http://grasswiki.osgeo.org/wiki/PostGIS\\_Topology](http://grasswiki.osgeo.org/wiki/PostGIS_Topology)

Cofunded by Municipality of Trento, Italy

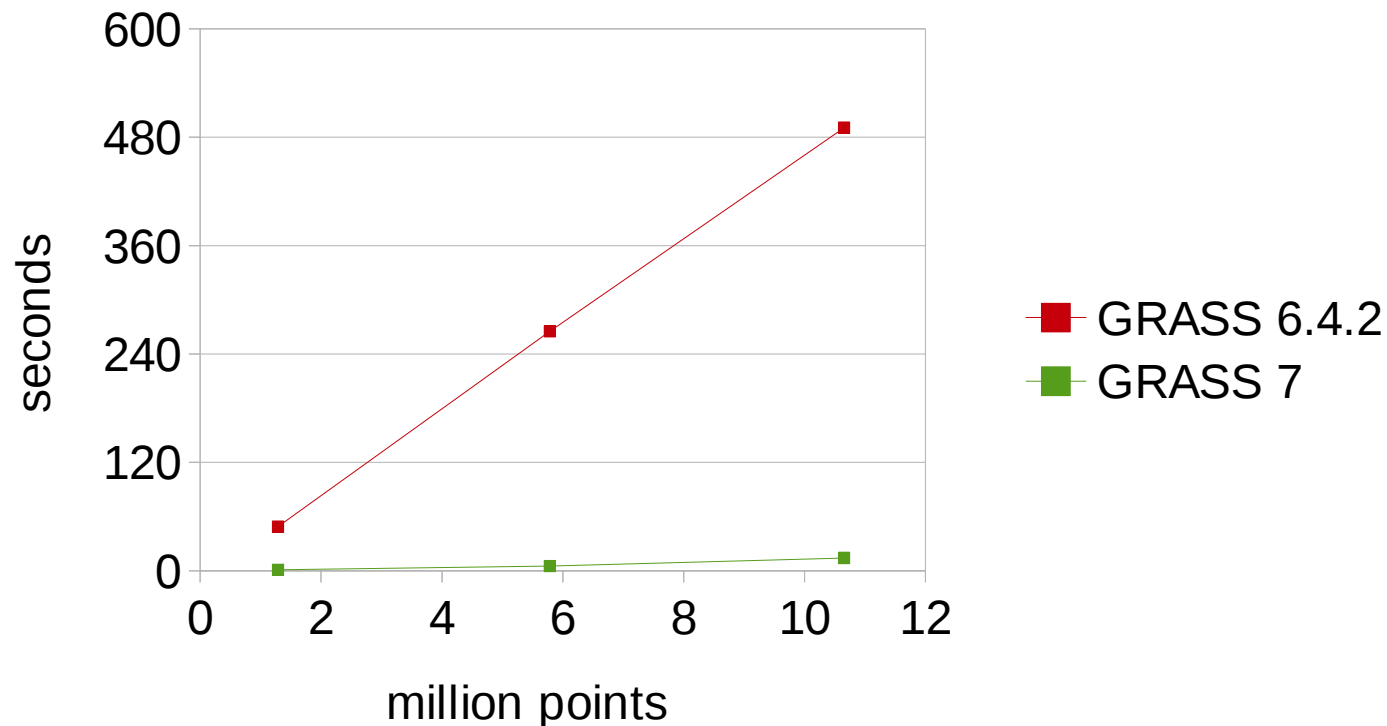
# News in GRASS 7's Vector Topology

## Spatial query example

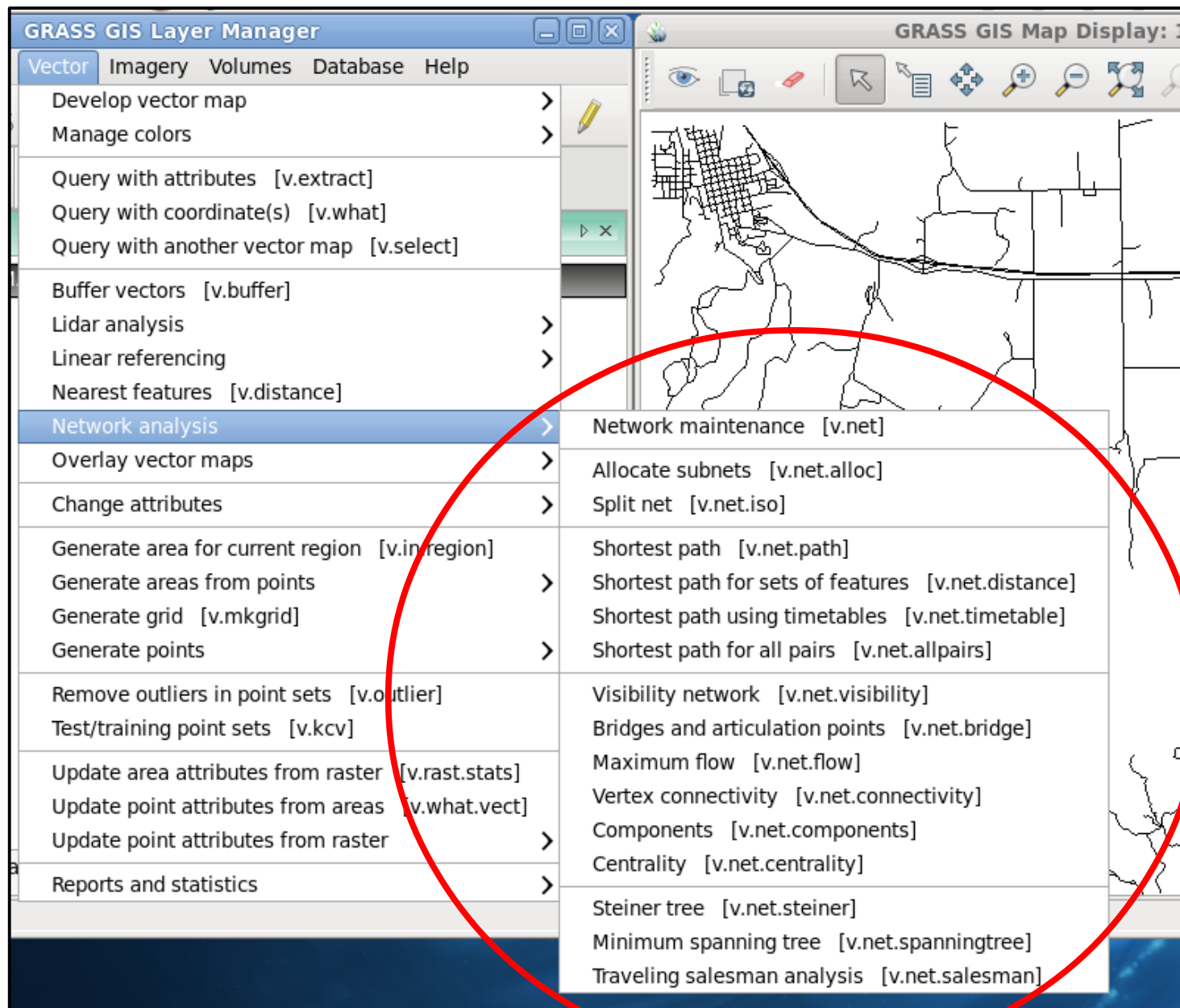
Query of vector point maps

GUI: click on vector map, what is there?

CLI: `v.what east_north=east,north`



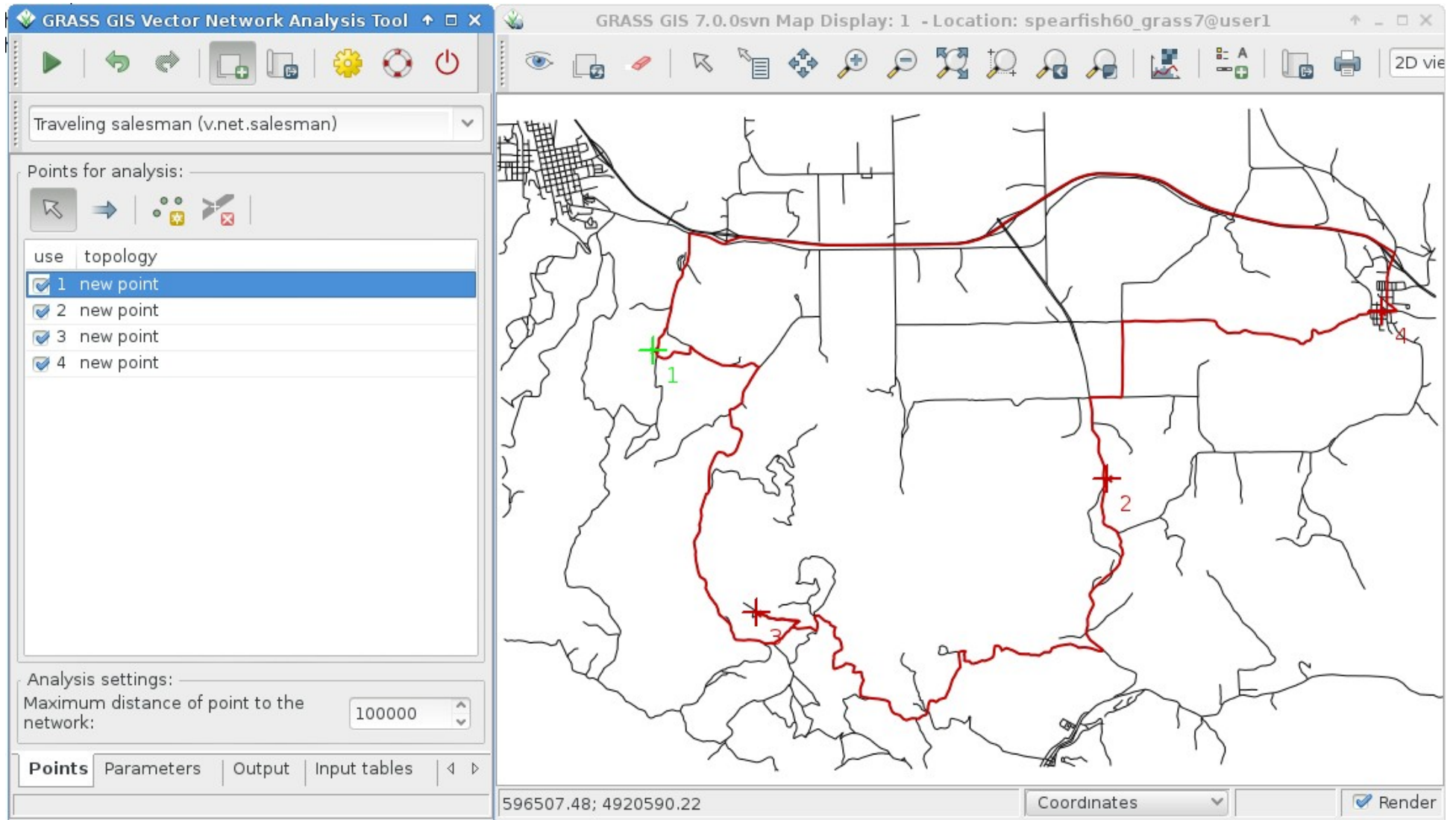
# Vector network analysis in GRASS



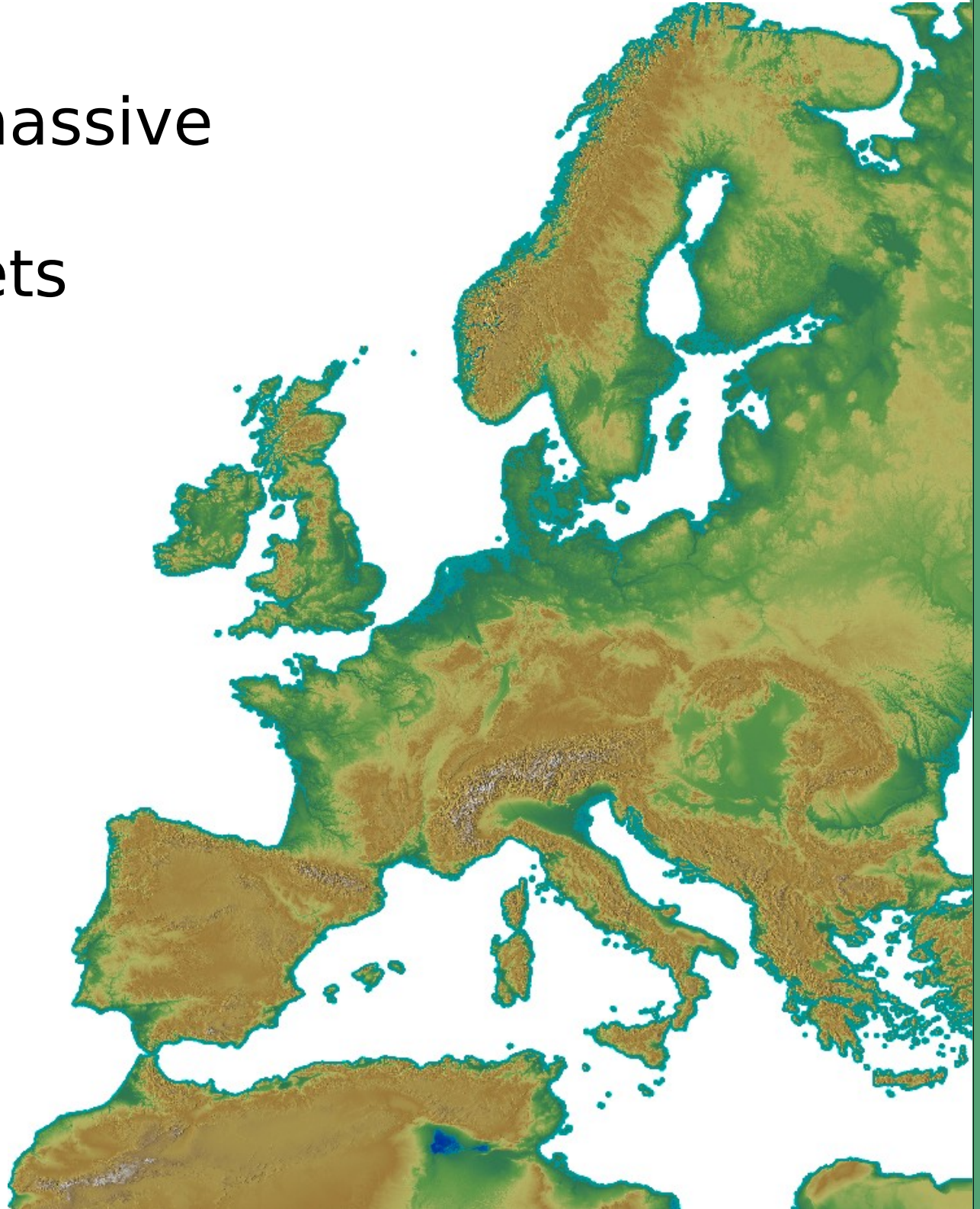
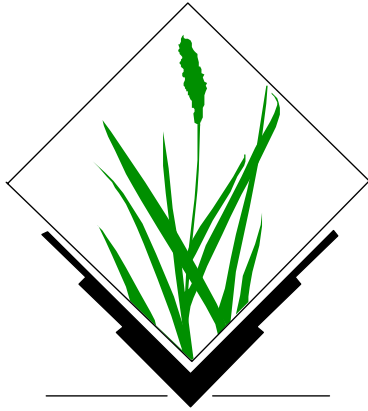


# Vector network analysis in GRASS

Example travelling salesman problem, 4 points to visit with optimal path



# Support for massive spatial datasets in GRASS GIS



# GRASS 7: Support for massive datasets

## What is massive?

Massive is relative to

Hardware resources

Software capabilities

Operating system capabilities

Limiting factors



RAM



Processing time



Disk space

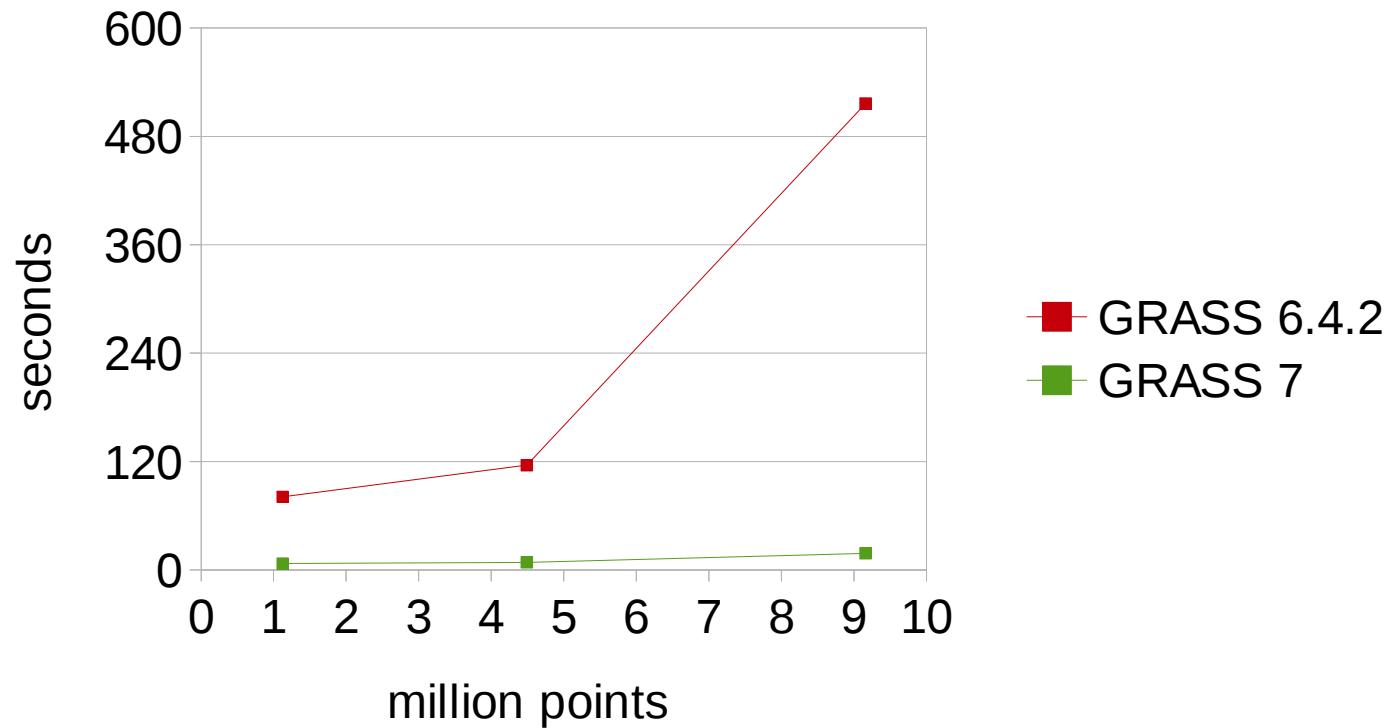


Largest supported file size



# GRASS 7: Support for massive datasets

Cost surfaces: *r.cost*



*Other speed figure:*  
**PCA of 30 million pixels  
in 6 seconds** on this small  
presentation laptop...

# New tools for hydrological modelling

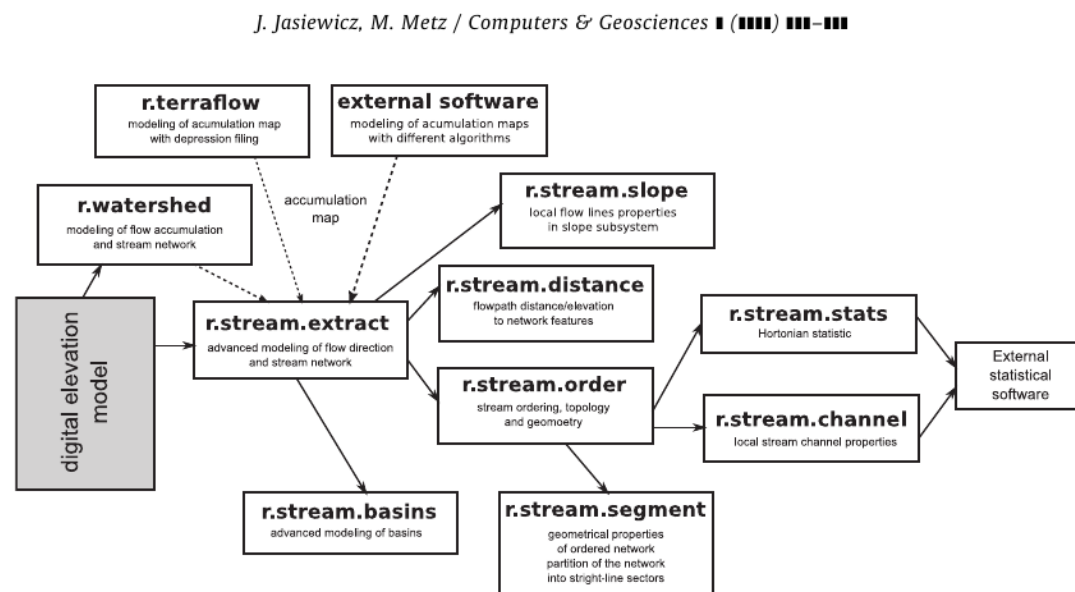


Fig. 2. The structure of the r.stream toolset and data flow between particular modules and external software.



## A new GRASS GIS toolkit for Hortonian analysis of drainage networks

Jarosław Jasiewicz<sup>a,\*</sup>, Markus Metz<sup>b</sup>

<sup>a</sup> Adam Mickiewicz University, Geology and Geoinformation Institute, Działowa 27 60-081 Poznań, Poland

<sup>b</sup> University of Ulm, Institute of Experimental Ecology, Allee 11, 89069 Ulm, Germany

### ARTICLE INFO

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Multiple flow direction

Basin delineation

GRASS GIS

Network topology

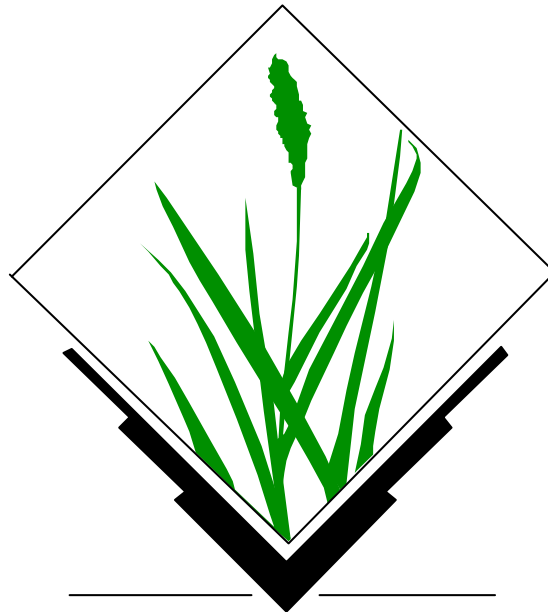
Modeling of accumulation maps

### ABSTRACT

The aim of this paper is to present a new GRASS GIS toolkit designed for Hortonian analysis of drainage networks. The r.stream toolset uses a multiple flow direction algorithm for stream network extraction as well as for calculating other hydrogeomorphological features in the catchment's area. As all GRASS GIS toolsets, r.stream consists of several separate modules that can extract stream networks from a spectrum of accumulation maps, order the extracted network using several ordering methods, do advanced modeling of basin's boundary, perform Hortonian statistics, calculate additional parameters such as flow path distance to watershed elements, partition ordered and unordered networks into near-straight-line sectors, and calculate sector directions. The package is free and open-source software, available for GRASS version 6.4 and later.

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# Programming own applications with GRASS GIS 7





# New GRASS 7 Python API

[http://grass.osgeo.org/wiki/GRASS\\_and\\_Python](http://grass.osgeo.org/wiki/GRASS_and_Python)



Page [Discussion](#)

Read [Edit](#) [View history](#)

## GRASS and Python

### Navigation

[Main Page](#)  
[Community](#)  
[Development](#)  
[Documents](#)  
[GRASS Help](#)  
[Recent changes](#)  
[Help](#)

### Toolbox

[What links here](#)  
[Related changes](#)  
[Upload file](#)  
[Special pages](#)  
[Printable version](#)  
[Permanent link](#)

### 1 Python SIGs

### 2 Writing Python scripts

[2.1 Python script ed](#)

[2.2 Using the GRA](#)

[2.3 Creating Python](#)

[2.3.1 MS-Wind](#)

[2.3.2 Linux](#)

[2.4 Running extern](#)

[2.5 Testing and inst](#)

[2.5.1 Debuggin](#)

[2.5.2 Installati](#)

### 3 Python extensions in C

[3.1 Python Scripting](#)

[3.2 Python Ctypes I](#)

[3.3 wxPython GUI c](#)

[3.4 Python-GRASS](#)

[3.5 Using GRASS g](#)

### 4 FAQ

### 5 Links

[5.1 General guides](#)

[5.2 Programming](#)

[5.3 Presentations](#)

Introduction to Vector classes — Python library documentation documentation - Konqueror

File Edit View Go Bookmarks Tools Settings Window Help

[http://grass.osgeo.org/grass71/manual...](#) Google

[Python library documentation documentation](#) » [PyGRASS documentation](#) »

[previous](#) | [next](#) | [modules](#) | [index](#)

## Introduction to Vector classes

Details about the architecture can be found in the [GRASS GIS 7 Programmer's Manual: GRASS Vector Library](#)

Instantiation and basic interaction.

```
>>> from pygrass.vector import VectTopo
>>> municip = VectTopo('boundary_municip_sqlite')
>>> municip.is_open()
False
>>> municip.mapset
''
>>> municip.exist() # check if exist, and if True set mapset
True
>>> municip.mapset
'user1'
```

Open the map with topology:

```
>>> municip.open()
```

get the number of primitive:

### Previous topic

[Introduction to Raster classes](#)

### Next topic

[Interface to GRASS GIS modules](#)

### Quick search

Enter search terms or a module, class or function name.

# New GRASS 7 Python API

*ISPRS Int. J. Geo-Inf.* **2013**, *2*, 201–219; doi:10.3390/ijgi2010201

OPEN ACCESS

ISPRS International  
Journal of  
**Geo-Information**  
ISSN 2220-9964  
www.mdpi.com/journal/ijgi

*Article*

## **Pygrass: An Object Oriented Python Application Programming Interface (API) for Geographic Resources Analysis Support System (GRASS) Geographic Information System (GIS)**

**Pietro Zambelli**<sup>1,\*</sup>, **Sören Gebbert**<sup>2</sup> and **Marco Ciolli**<sup>1</sup>

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Tel.: +39-46-128-2696.

*Received: 1 January 2013; in revised form: 21 January 2013 / Accepted: 21 February 2013 /*

*Published: 11 March 2013*

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**Abstract:** PyGRASS is an object-oriented Python Application Programming Interface (API) for Geographic Resources Analysis Support System (GRASS) Geographic Information System (GIS), a powerful open source GIS widely used in academia, commercial settings and governmental agencies. We present the architecture of the PyGRASS library, covering interfaces to GRASS modules, vector and raster data, with a focus on the new capabilities that it provides to GRASS users and developers. Our

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All former shell scripts have been rewritten to Python in GRASS GIS 7:

→ re-use as example!

<http://dx.doi.org/10.3390/ijgi2010201>

# GRASS 7 Programmer's manual

<http://grass.osgeo.org/programming7/>

The screenshot shows a web browser window titled "GRASS GIS 7 Programmer's Manual: GRASS 7 Programmer's Manual - Konqueror". The address bar shows the URL <http://grass.osgeo.org/programming7/>. The page content includes a navigation menu on the left with categories like Libraries, GUI, and File structure. The main content area is titled "GRASS 7 Programmer's Manual" and contains an introduction to GRASS GIS, its licensing (GNU GPL), and the manual's purpose. It also mentions the GRASS Development Team and the GNU Free Documentation License (GFDL). The footer indicates the page was generated on Sat Sep 6 2014 05:48:30 for GRASS GIS 7 Programmer's Manual by doxygen 1.8.5.

GRASS GIS 7 Programmer's Manual 7.1.svn(2014)-r61813

Main Page Related Pages Namespaces Data Structures Files Search

GRASS GIS 7 Programmer's Manual

GRASS 7 Programmer's Manual

- Libraries
  - Core libraries
  - Interfaces
    - ▶ Further libraries
  - GUI
  - File structure of GRASS Location
    - ▶ Compiling and Installing GRASS Modules
    - Multiple-Architecture Conventions
      - ▶ Vector modules and their parameters
  - ▶ GRASS wxPython-based GUI
  - ▶ GRASS Cairo Display Driver
  - ▶ GRASS testing normality & exponential smoothing
  - ▶ GRASS Cluster analysis statistics Library
  - ▶ GRASS DataBase Management Interface
  - ▶ GRASS Display Library
  - ▶ GRASS GIS Library
  - ▶ GRASS Numerical math interface
  - ▶ GRASS Partial differential equations Library
  - ▶ GRASS Imagery Library
  - ▶ GRASS Data Elements Management Library

**GRASS 7 Programmer's Manual**

**GRASS GIS** (Geographic Resources Analysis Support System) is an open source, free software *Geographical Information System* (GIS) with raster, topological vector, image processing, and graphics production functionality that operates on various platforms through a graphical user interface (GUI) or command line interface (CLI). It is released under [GNU General Public License](#) (GPL).

This manual introduces the reader to the *Geographic Resources Analysis Support System* from the programming perspective. Design theory, system support libraries, system maintenance, and system enhancement are all presented. This work is part of ongoing research being performed by the [GRASS Development Team](#), an international team of programmers, GRASS module authors are cited within their module's source code and the contributed manual pages.

© 2000-2014 by the GRASS Development Team

This manual is published under [GNU Free Documentation License](#) (GFDL), and comes with ABSOLUTELY NO WARRANTY. The development of GRASS software and this manual is kindly supported by the [Open Source Geospatial Foundation](#), who provides the GRASS main infrastructure.

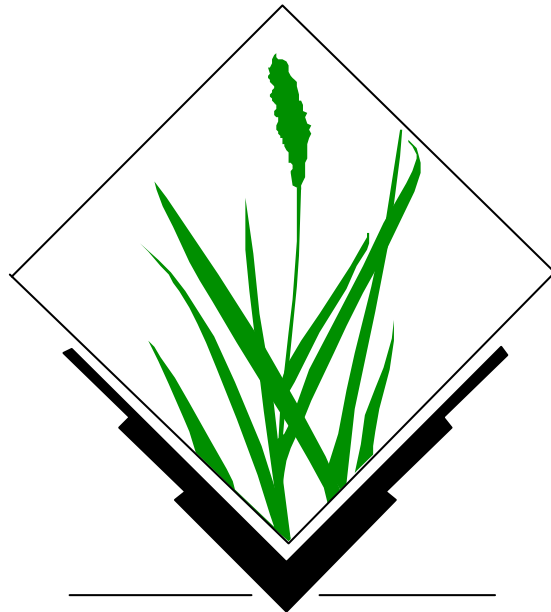
Main web site: <http://grass.osgeo.org>

Generated on Sat Sep 6 2014 05:48:30 for GRASS GIS 7 Programmer's Manual by [doxygen](#) 1.8.5



# GRASS GIS as Open Source GIS backbone:

## Connecting to other software packages



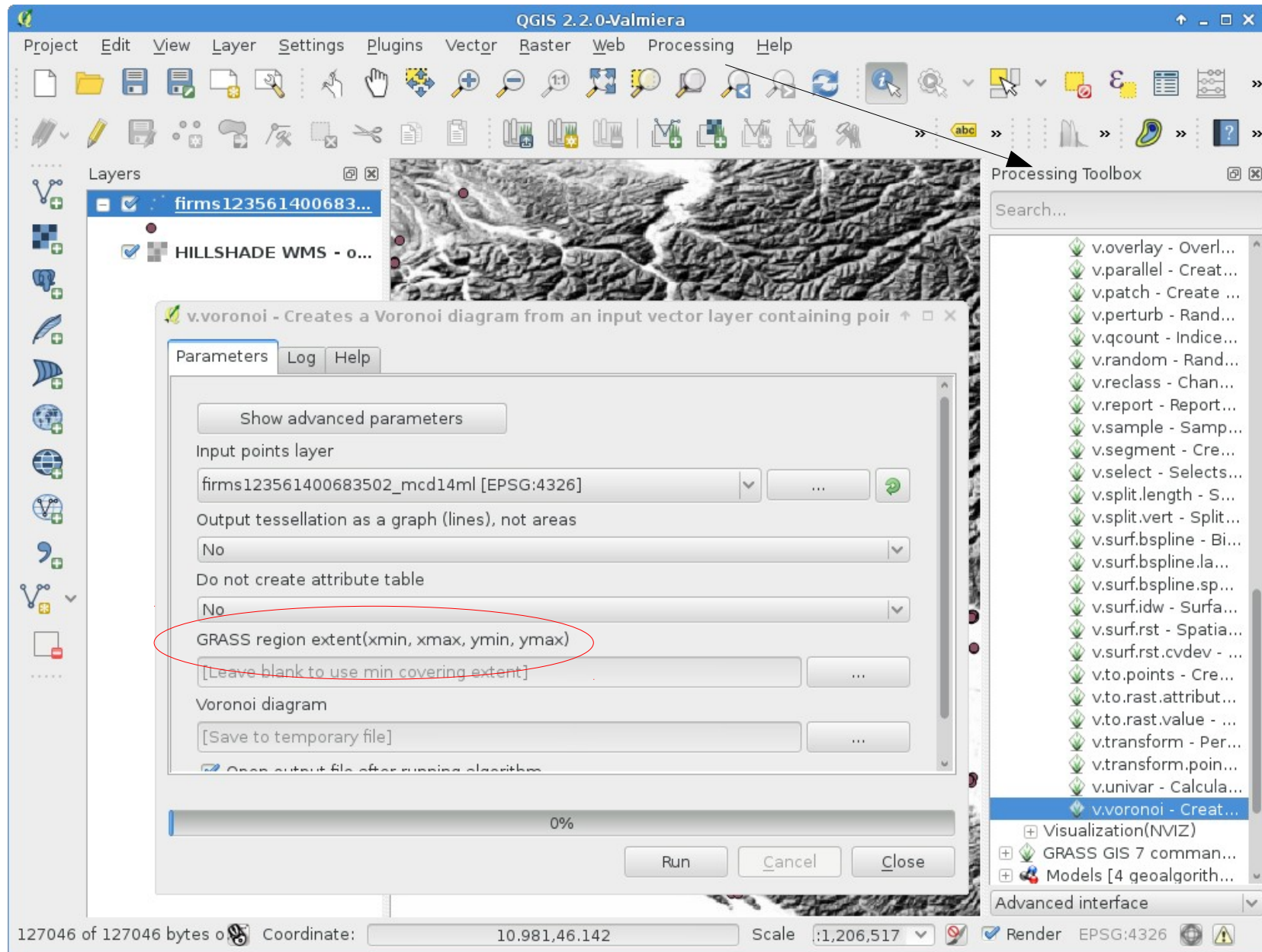
# GRASS and QGIS Integration: Processing

The screenshot displays the QGIS 2.2.0-Valmiera interface. The main map area shows a purple-shaded polygon representing a geographic area. The 'Layers' panel on the left lists 'zipcodes wake'. The 'Processing Toolbox' on the right shows a list of algorithms, with 'v.dissolve - Dissolves boundaries between adjacent areas sharing a common...' selected. The 'Parameters' dialog for this tool is open, showing the 'Input vector layer' as 'zipcodes\_wake [USER:100000]' and a list of columns for dissolving boundaries, with 'ZIPNAME' selected. Below the dialog, two maps are shown side-by-side: the left map displays the original purple-shaded area with internal boundaries, and the right map shows the result of the 'v.dissolve' operation, where the area is now a single solid orange polygon with all internal boundaries removed.

**Dissolving geometry by string column attributes: *Processing* calls GRASS GIS in a virtual session which delivers the result back (here: SHAPE file)**

# Integration of GRASS GIS with QGIS, PostGIS, OGC

Geoprocessing of an external wildfire point layer:  
PostGIS or WFS -> QGIS → Processing → GRASS GIS



# GRASS and R Integration

GRASS 7.0.svn (nc\_spm\_08\_grass7):~ > R

R version 3.0.1 (2013-05-16) -- "Good Sport"

Copyright (C) 2013 The R Foundation for Statistical Computing

Platform: x86\_64-redhat-linux-gnu (64-bit)

```
> library(spgrass6)
```

```
Loading required package: sp
```

```
Loading required package: XML
```

GRASS GIS interface loaded with GRASS version: GRASS 7.0.svn (2013)

and location: nc\_spm\_08\_grass7

```
>
```

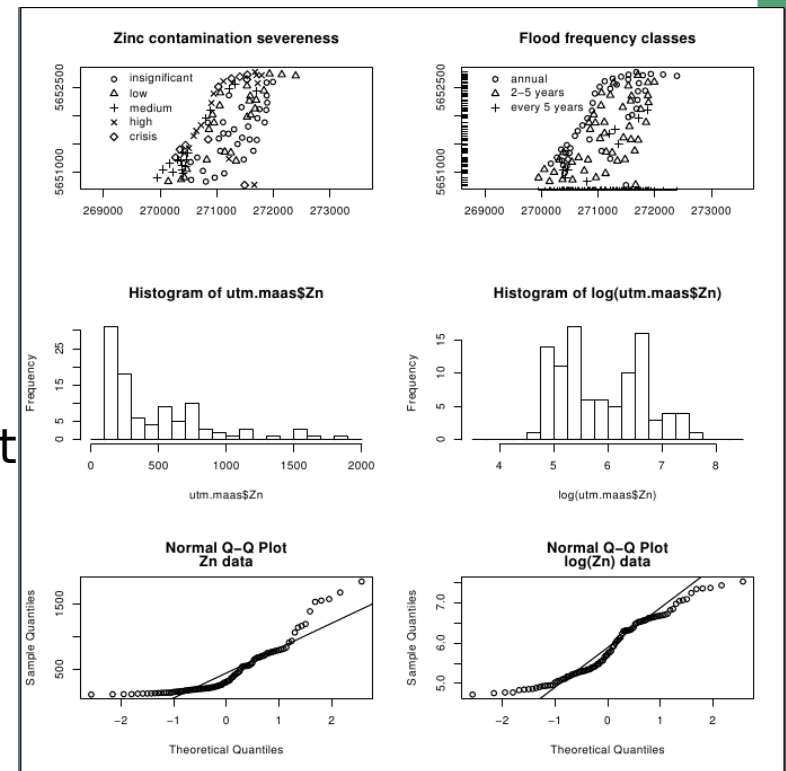
```
> myrast <- readRAST6(c("geology", "elevation"), cat=c(TRUE, FALSE))
```

```
> myvect <- readVECT6("roads")
```

```
...
```

```
> writeRAST6(myrast, "elev_filt", zcol="elev")
```

```
...
```





# GRASS 7: Native WPS Support



```
r.grow --wps-process-description
```

```
<?xml version="1.0" encoding="UTF-8"?>
<wps:ProcessDescriptions xmlns:wps="http://www.opengis.net/wps/1.0.0"
xmlns:ows="http://www.opengis.net/ows/1.1"
xmlns:xlink="http://www.w3.org/1999/xlink"
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="http://www.opengis.net/wps/1.0.0
http://schemas.opengis.net/wps/1.0.0/wpsDescribeProcess_response.xsd"
service="WPS" version="1.0.0" xml:lang="en-US">
  <ProcessDescription wps:processVersion="1" storeSupported="true" statusSupported="true">
    <ows:Identifier>r.grow</ows:Identifier>
    <ows:Title>Generates a raster map layer with contiguous areas grown by one cell.</ows:Title>
    <ows:Abstract>The manual page of this module is available here: http://grass.osgeo.org/grass70/manuals/html70_use
    <ows:Metadata xlink:title="raster" />
    <DataInputs>
      <Input minOccurs="1" maxOccurs="1">
        <ows:Identifier>input</ows:Identifier>
        <ows:Title>Name of input raster map</ows:Title>
        <ComplexData maximumMegabytes="2048">
          <Default>
            <Format>
              <MimeType>image/tiff</MimeType>
            </Format>
          </Default>
          <Supported>
            <Format>
              <MimeType>image/tiff</MimeType>
            </Format>
            <Format>
              <MimeType>image/geotiff</MimeType>
            </Format>
            <Format>
              <MimeType>application/geotiff</MimeType>
            </Format>
          </Supported>
        </ComplexData>
      </Input>
    </DataInputs>
  </ProcessDescription>
</wps:ProcessDescriptions>
```

*Web Processing  
Service*

<http://grasswiki.osgeo.org/wiki/WPS>

# Image processing

*Improved modules:*

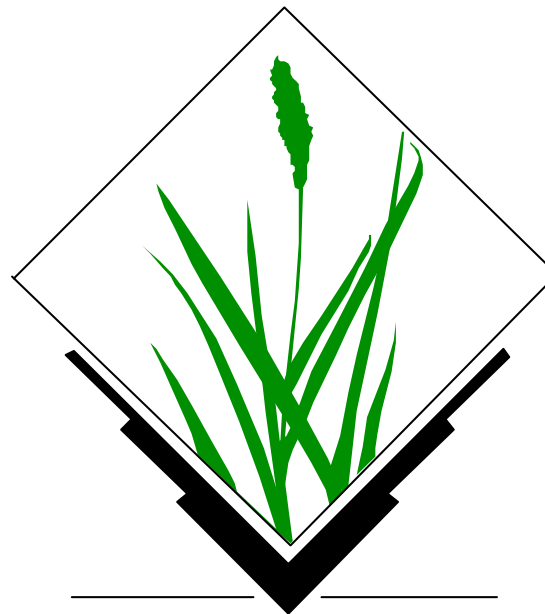
Georectification

Orthorectification

Atmospheric correction

Terrain correction

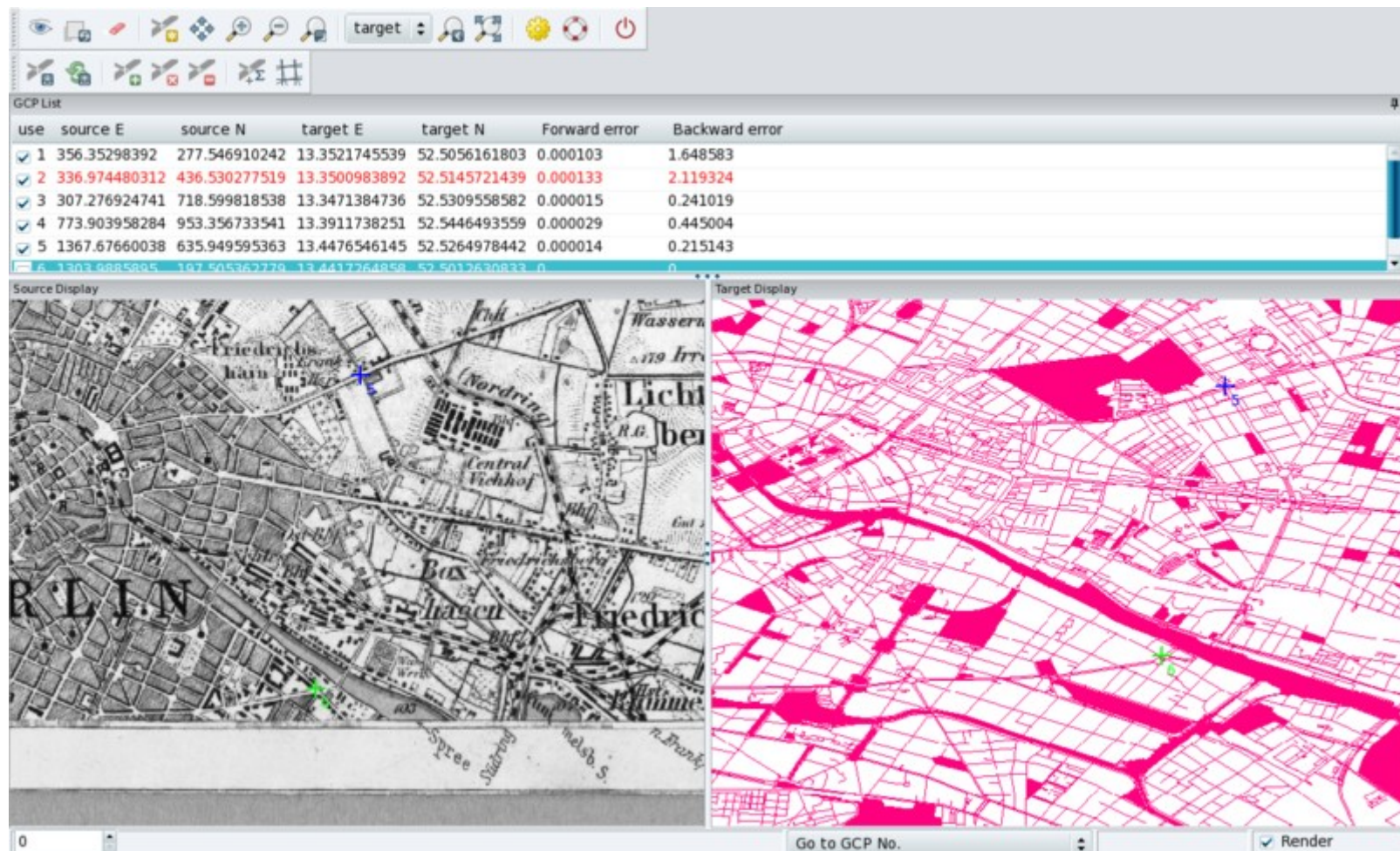
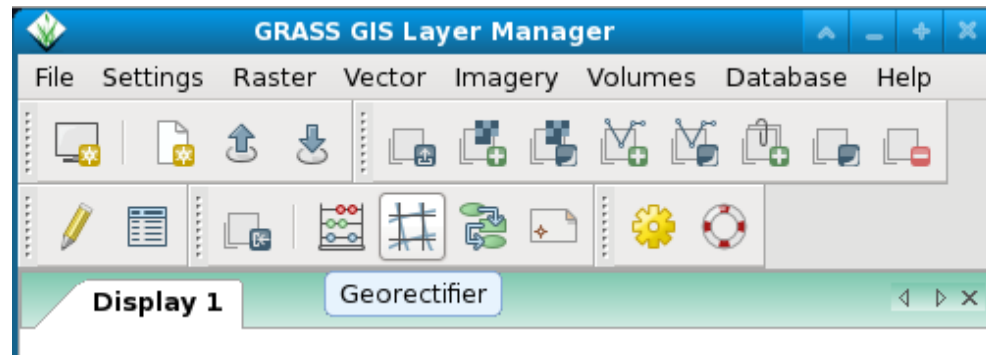
Landsat cloud detection



# GRASS 7: New geocoding tool

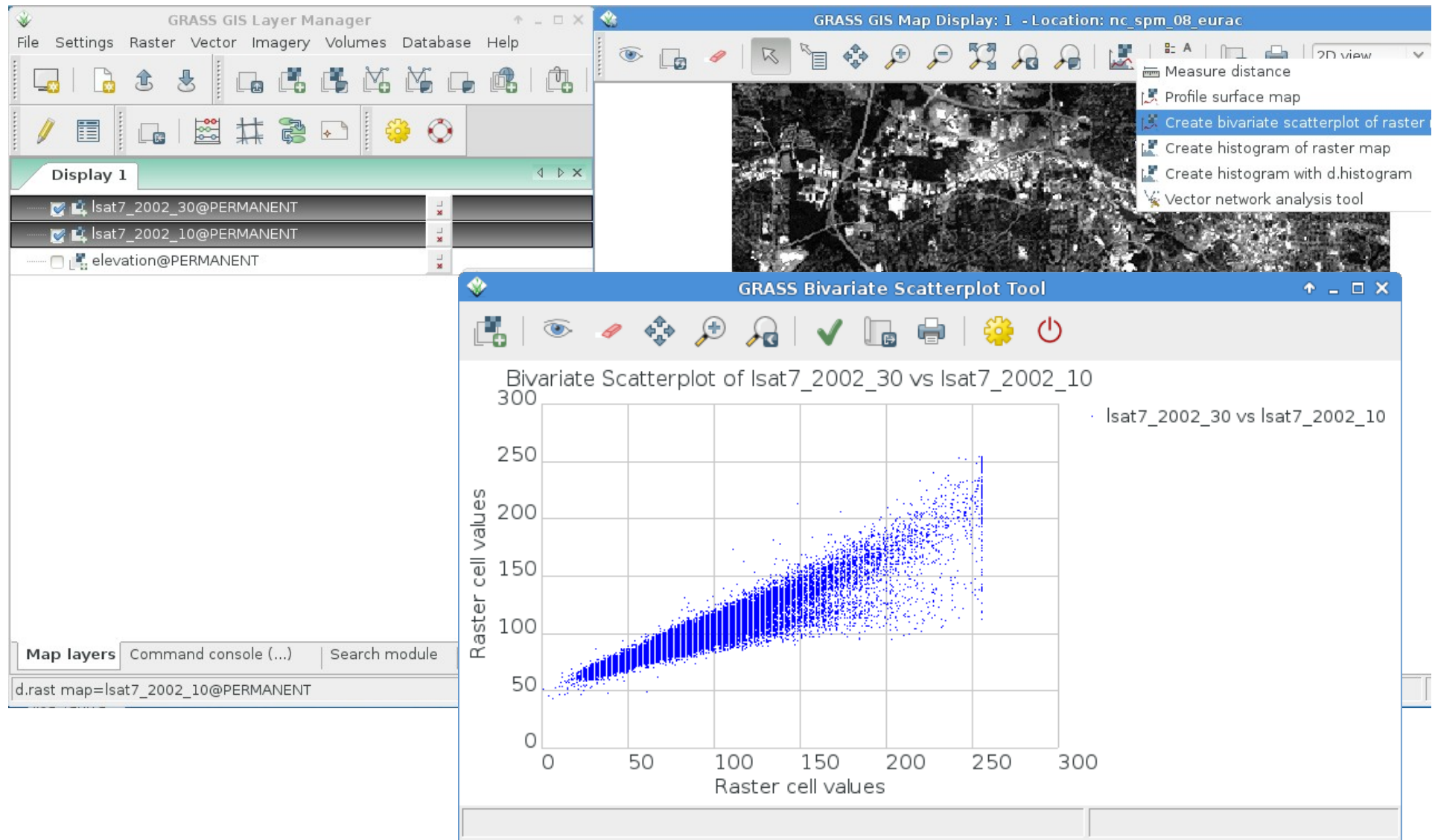
## Image/Map rectifier

For raster (imagery, historic scans) and vector maps



# GRASS 7: New bivariate Scatterplots

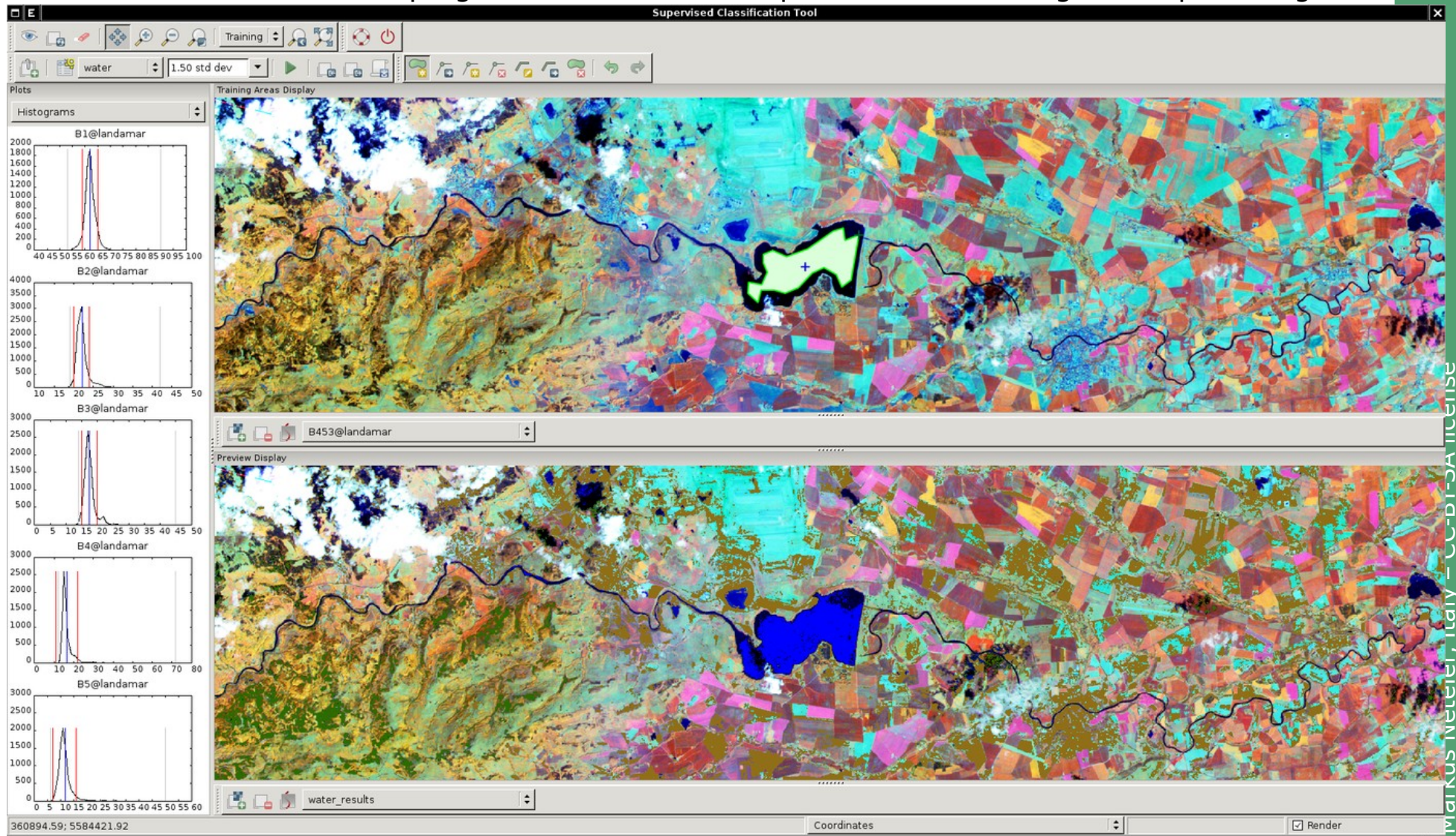
LANDSAT 7 2002 **channels 1 and 3** of Wake county, NC





# GRASS 7: Supervised image classification

<http://geo.fsv.cvut.cz/~landa/publications/2012/ogrs2012/poster/figures/>



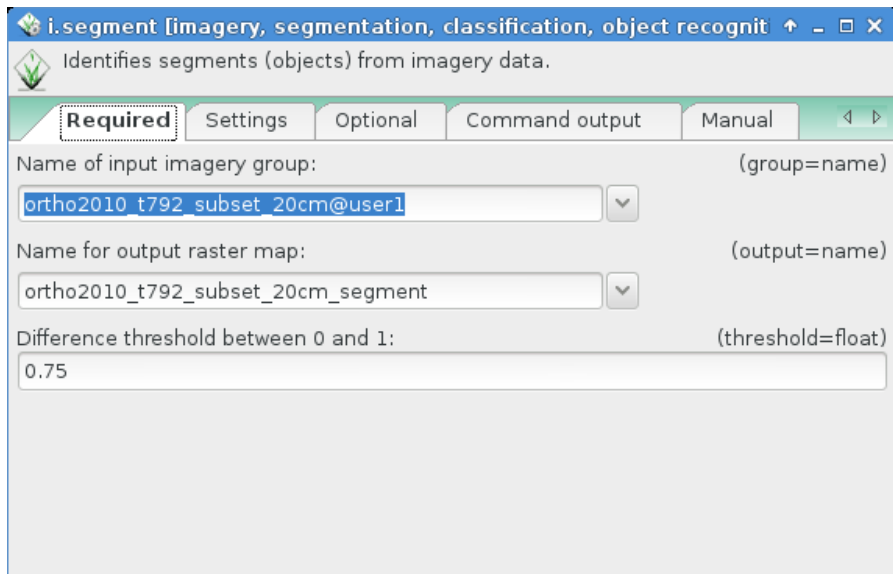
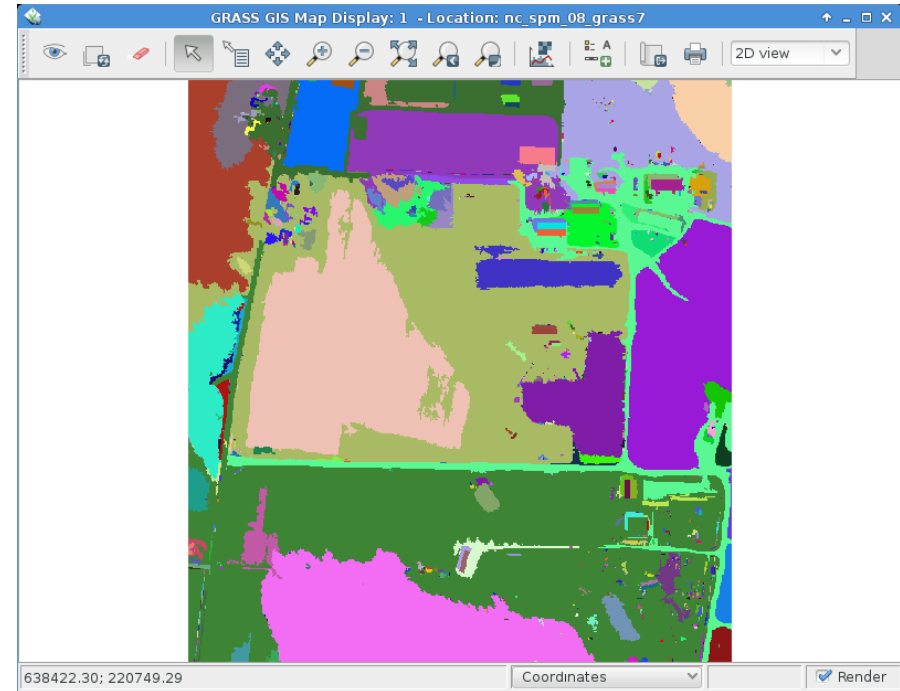
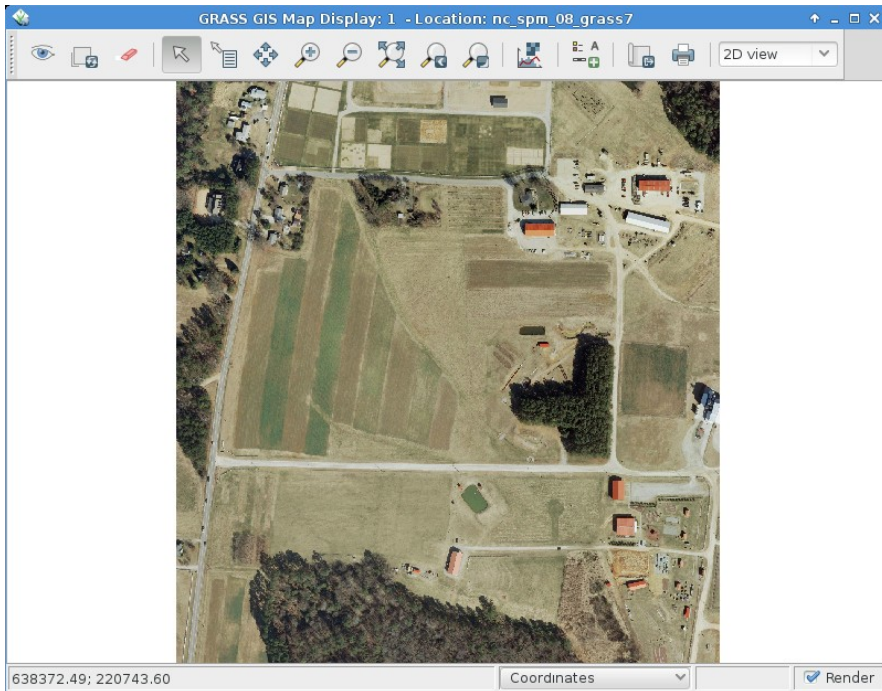
Tool for supervised classification of imagery data.

Generates spectral signatures for an image by allowing the user to outline regions of interest.



# GRASS 7: Unsupervised image classification

**i.segment** - Identifies segments (objects) from imagery data.



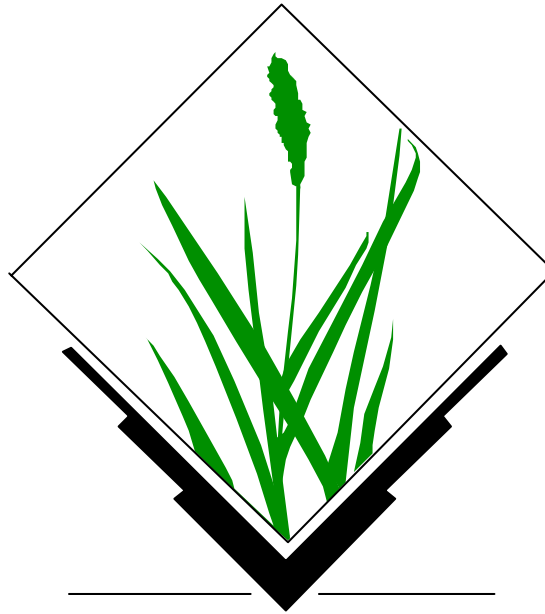
Pietro Zambelli

# GRASS 7: New cool stuff: massive data processing

- Since **2005** GRASS GIS is running **natively** on 64bit CPUs
- GRASS GIS 7 also offers Large File Support on 32bit Windows
- Installed on Grids and TOP500 supercomputers (AKKA Umeå, ENEA Frascati, Aurel Bratislava, ...)
- Runs on Linux, AIX, Solaris, freeBSD, netBSD, ...
- Various ways of parallelization



# GRASS GIS 7 Temporal Framework: Time-series support





# New Space-Time functionality in GRASS 7

## Temporal data processing in GRASS GIS

The temporal GIS framework in GRASS introduces three new datatypes that are designed to handle time series data:

- *Space time raster datasets* (strds) are designed to manage raster map time series. Modules that process strds have the naming prefix *t.rast*.
- *Space time 3D raster datasets* (str3ds) are designed to manage 3D raster map time series. Modules that process str3ds have the naming prefix *t.rast3d*.
- *Space time vector datasets* (stvds) are designed to manage vector map time series. Modules that process stvds have the naming prefix *t.vect*.

## Temporal data management in general

List of general management modules:

- [t.connect](#)
- [t.create](#)
- [t.remove](#)
- [t.register](#)
- [t.unregister](#)
- [t.info](#)
- [t.list](#)
- [t.rast3d.list](#)
- [t.vect.list](#)
- [t.vect.db.select](#)
- [t.sample](#)
- [t.support](#)
- [t.topology](#)

### Export/import conversion

- [t.rast.export](#)
- [t.rast.import](#)
- [t.rast.out.vtk](#)
- [t.rast.to.rast3](#)
- [r3.out.netcdf](#)
- [t.vect.export](#)

### Statistics and gap filling

- [t.rast.gapfill](#)
- [t.rast.univar](#)

### Querying and map calculation

- [t.rast.list](#)
- [t.rast.extract](#)
- [t.rast.gapfill](#)
- [t.rast.mapcalc](#)
- [t.rast3d.extract](#)
- [t.rast3d.mapcalc](#)
- [t.rast3d.univar](#)
- [t.vect.extract](#)
- [t.vect.import](#)
- [t.vect.observe.strds](#)
- [t.vect.univar](#)
- [t.vect.what.strds](#)

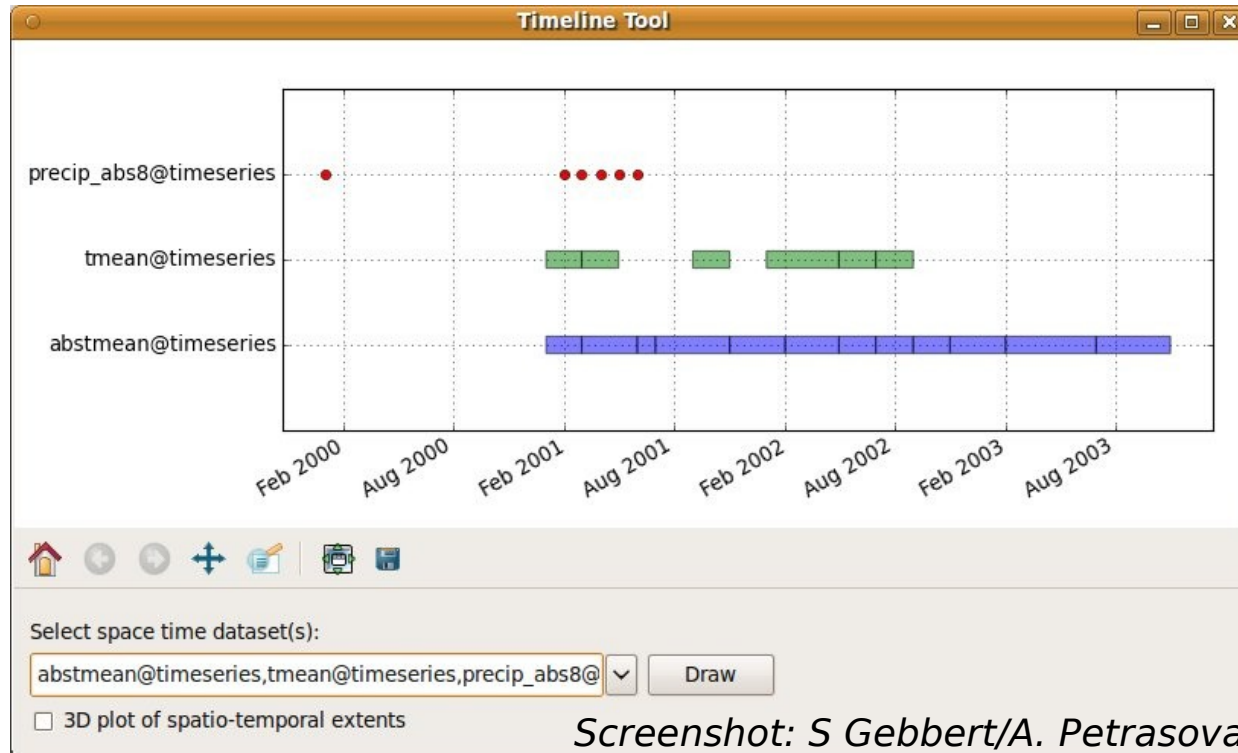
### Aggregation

- [t.rast.aggregate.ds](#)
- [t.rast.aggregate](#)
- [t.rast.series](#)

Space time datasets are stored in a temporal database. SQLite3 or PostgreSQL are supported as SQL database back end. Connection settings are performed with [t.connect](#). As default a sqlite3 database will be created in the PERMANENT mapset that stores all space time datasets and registered time series maps from all mapsets in the location.

Gebbert, S., Pebesma, E., 2014. *TGRASS: A temporal GIS for field based environmental modeling*. Environmental Modelling & Software 53, 1-12. (DOI)

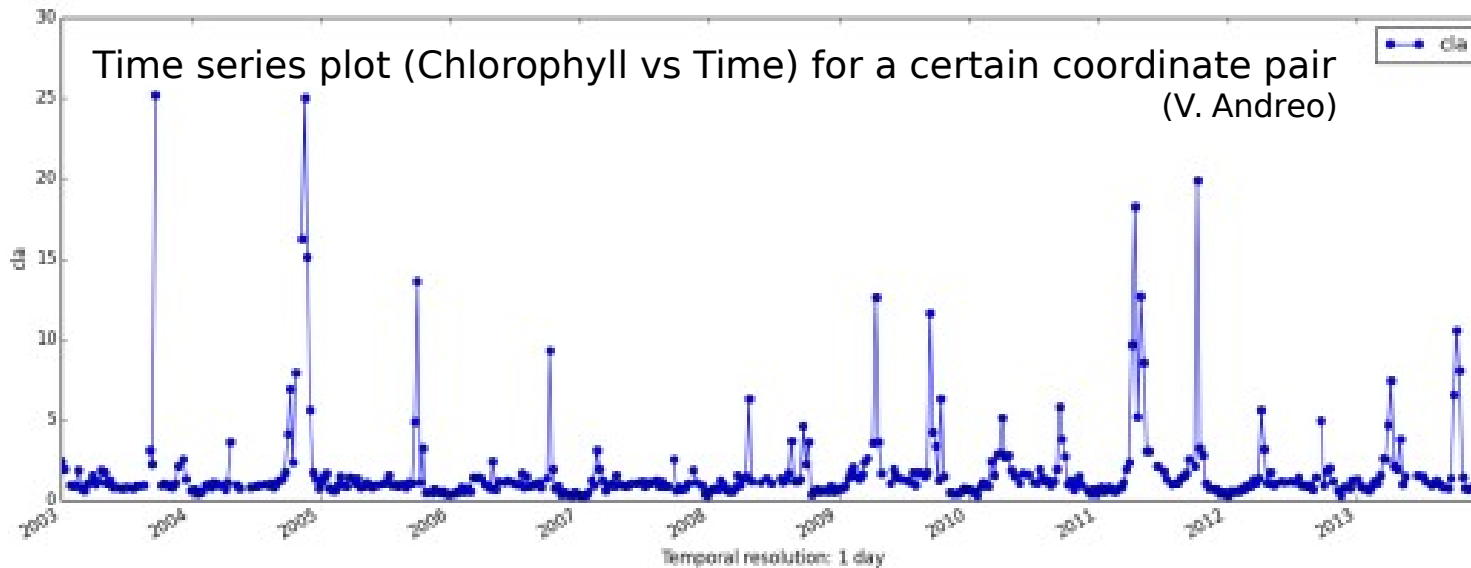
# New Space-Time functionality in GRASS 7



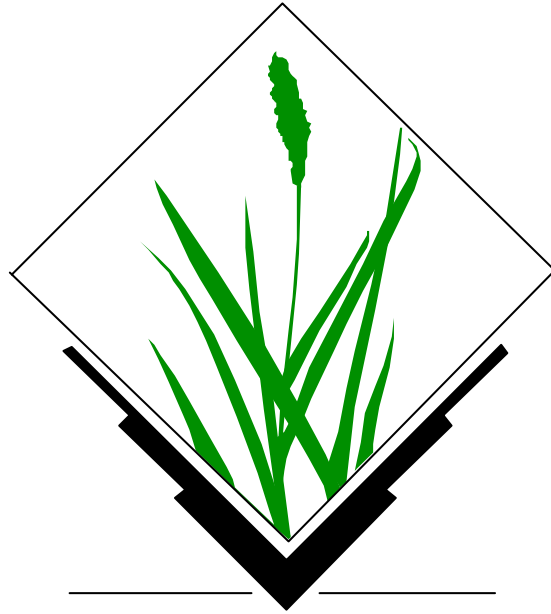
Monthly avg LST:  
01/2002

1000 km  
N

Screenshot: S Gebbert/A. Petrasova



# Visualization



# GRASS 7: New animation tool for time series

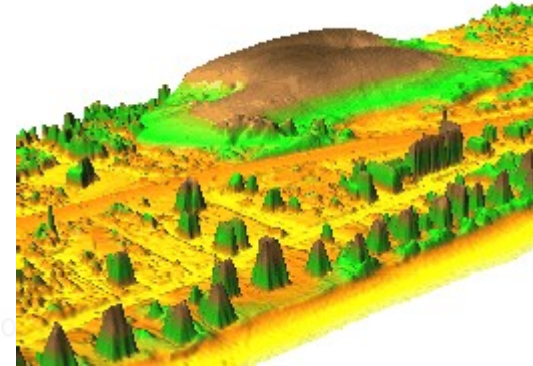
The **Animation Tool** is a [wxGUI](#) component for animating a series of GRASS raster maps or a space time raster dataset (created by t.\* modules).

Animation Tool allows you to:

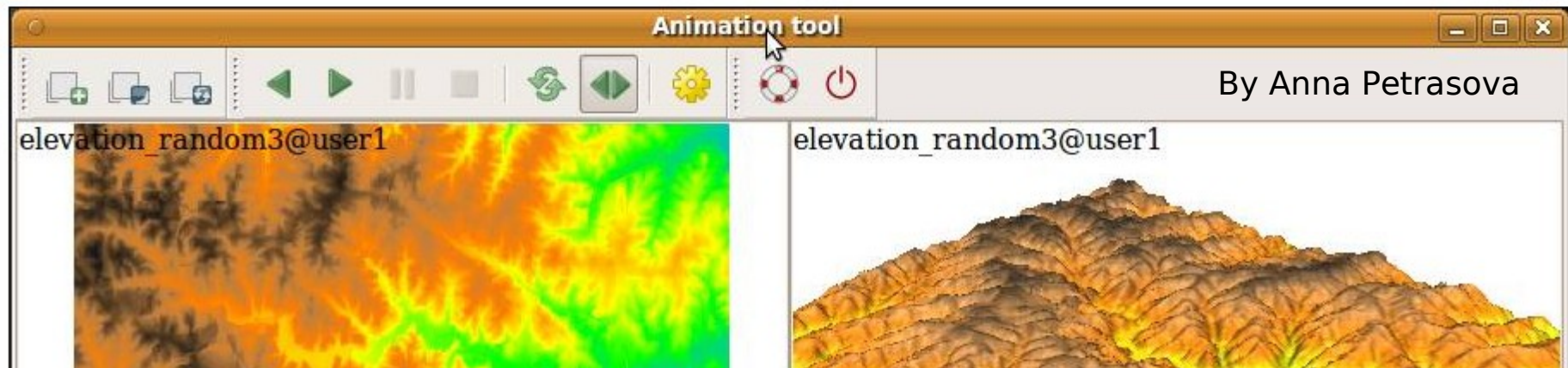
- display up to 4 synchronized animations
- control the animation speed
- interactively change active frame using a slider
- visualize space time datasets with unequally spaced intervals
- animate 3d view (partially implemented)

3D view animation enables to animate raster (as an elevation map or a color map) or vector data. `m.nviz.image` is used. To display 3D view animation follow these steps:

- open GRASS GUI, load maps and start 3D view
- set view, light and other parameters as you like
- save workspace file
- add new animation in Animation Tool, choose 3D view mode
- choose data (series of maps or space time dataset) used for animation
- set workspace file
- choose parameter (parameter of `m.nviz.image`) to animate (e.g. `color_map`)



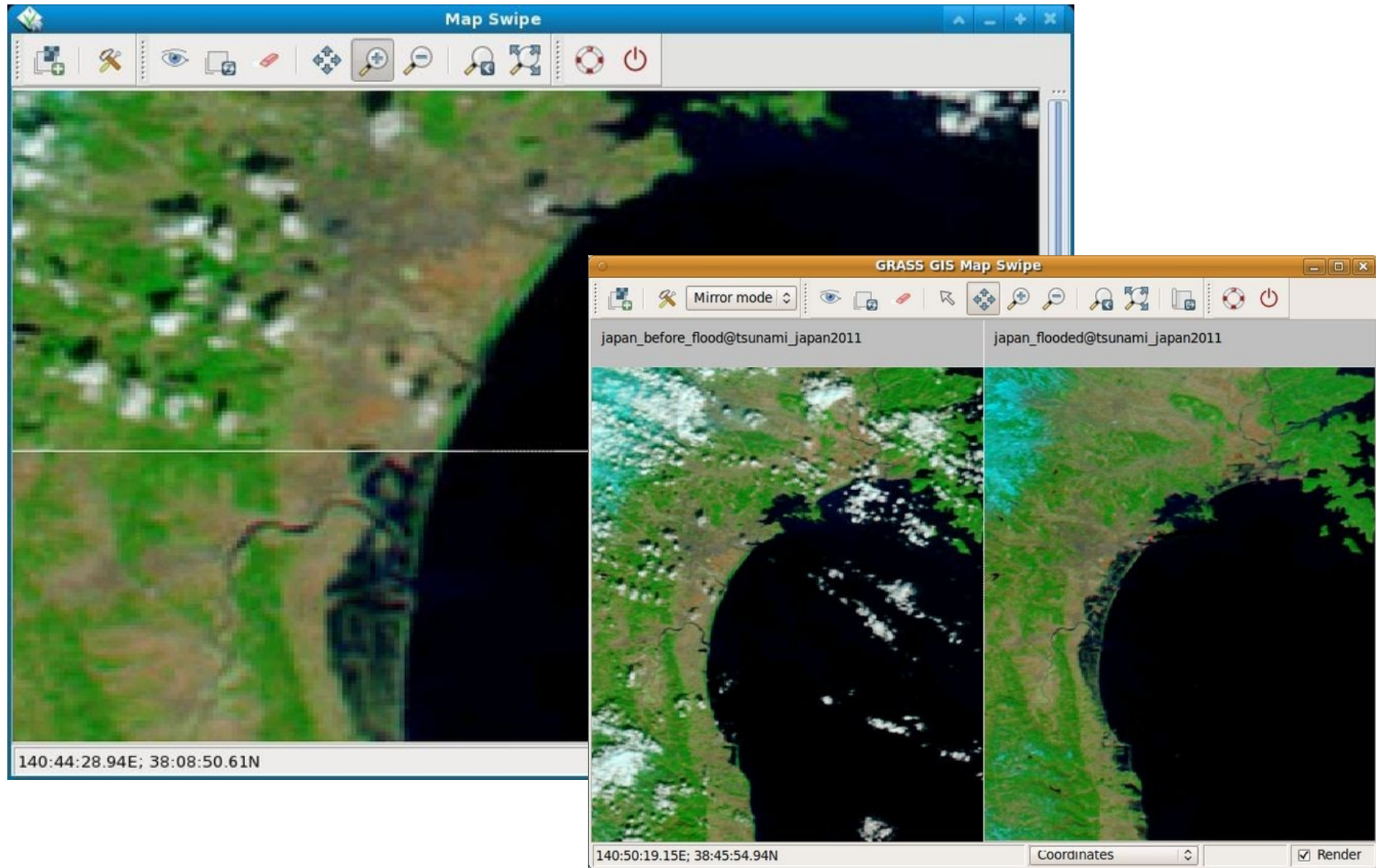
Nagshead LiDAR time series: dune moving over 9 years (NC, USA)



<http://grass.osgeo.org/grass70/manuals/g.gui.animation.html>

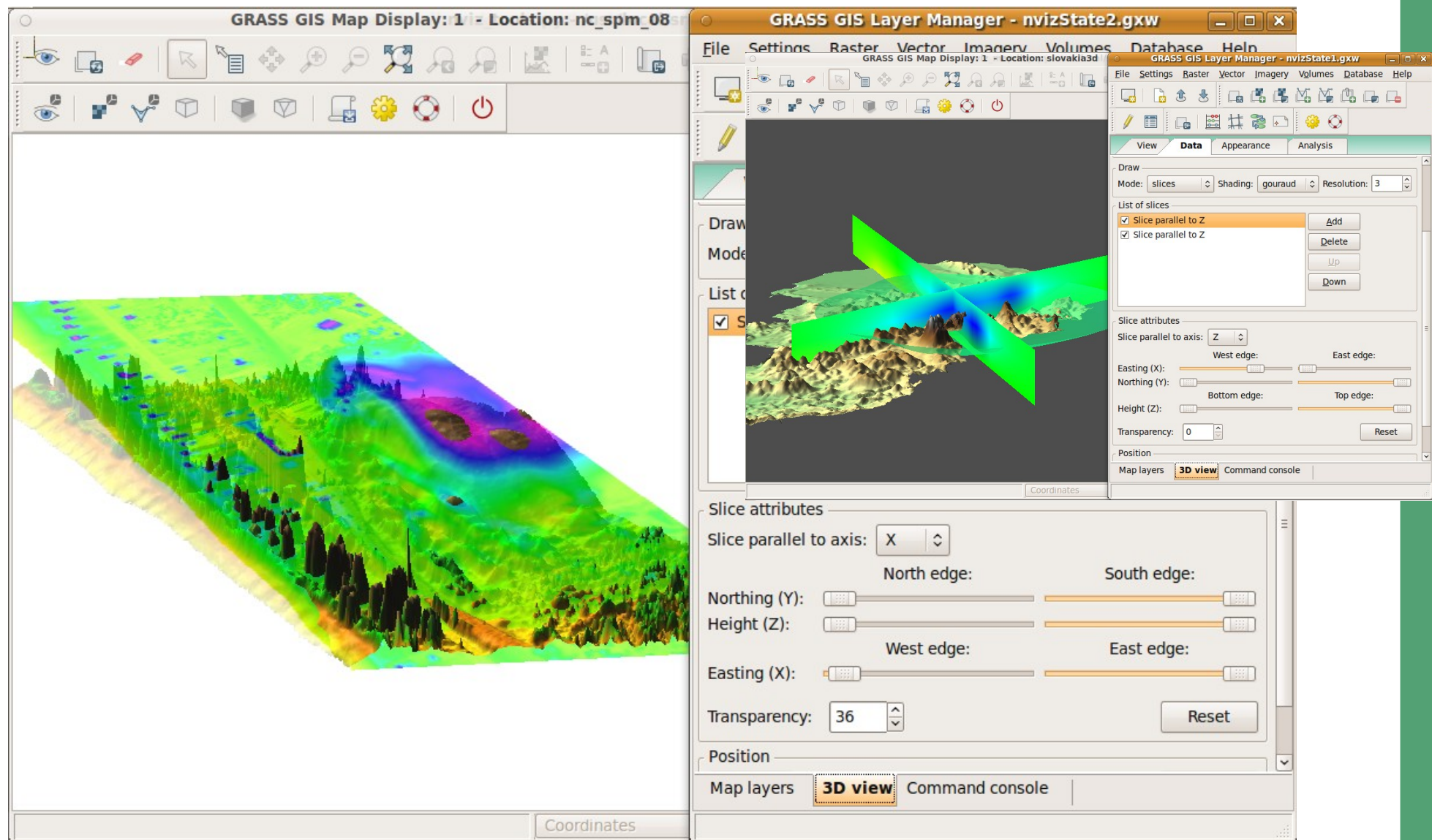


# New Map swiping tool for multitemporal maps



**Pre and post disaster images** of the tsunami in Japan in 2011  
(MODIS images taken on February 26 and March 13, 2011)

# GRASS 7: New visualization tool: wxNVIZ

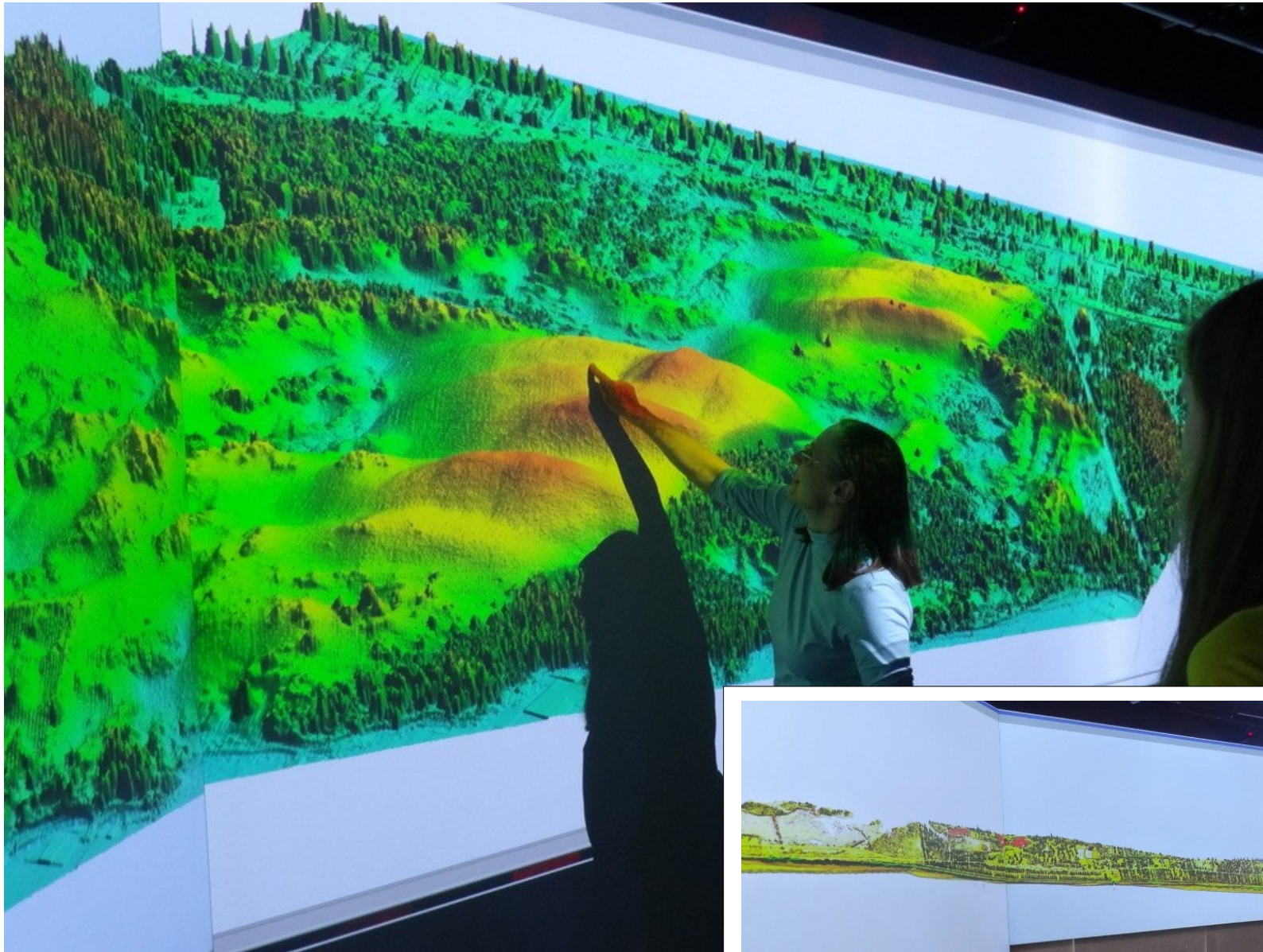


<http://grasswiki.osgeo.org/wiki/WxNVIZ>

Programming/screenshot:  
Anna Petrasova



# New visualization methods(NC state university)



**GRASS GIS  
goes  
theatre**

LiDAR derived DSM: 100k x 50k pixels



# GRASS GIS as a platform for sustainable Open Science

## GRASS GIS software offers to you:

- **Reproducibility:** Open source is the natural habitat for science and research
- **Return of Investment:**  
Example *r.mapcalc*: available since 1985, continuously developed, user can still run old scripts in latest GRASS GIS 7
- **Auto-documentation:** map and command history preserved “forever”
- **Reliability:** Testing and quality control system (in progress) integrated into the software itself
- **Longevity for Open Science:** code integrated into GRASS “survives” even if original authors would not continue

### In a Nutshell, GRASS GIS...

- ... has had 50,946 commits made by 71 contributors representing 1,344,395 lines of code
- ... is mostly written in C with an average number of source code comments
- ... has a well established, mature codebase maintained by a large development team with stable Y-O-Y commits
- ... took an estimated 378 years of effort (COCOMO model) starting with its first commit in December, 1999 ending with its most recent commit 2 months ago

[https://www.openhub.net/p/grass\\_gis](https://www.openhub.net/p/grass_gis)



# Where is the stuff?

## GRASS GIS 7 Software:

*Free download for MS Windows, MacOSX, Linux and source code:*

<http://grass.osgeo.org/download/>

*Addons (user contributed extensions):*

[http://grasswiki.osgeo.org/wiki/GRASS\\_AddOns](http://grasswiki.osgeo.org/wiki/GRASS_AddOns)

## Free sample data:

*Rich data set of North Carolina (NC)*

*... available as GRASS GIS location and in common GIS formats*

<http://grass.osgeo.org/download/sample-data/>

## User Help:

**Mailing lists** (also in different languages):

<http://grass.osgeo.org/support/>

**Wiki:**

<http://grasswiki.osgeo.org/wiki/>

**Manuals:**

<http://grass.osgeo.org/documentation/manuals/>



<http://grass.osgeo.org>

<http://trac.osgeo.org/grass/wiki/Grass7/NewFeatures>

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[neteler@osgeo.org](mailto:neteler@osgeo.org)



**Coming soon:  
GRASS GIS 7!**

**THANKS**

